

On the asymptotic behaviors of solutions to stochastic obstacle problems
Large deviations & invariant measures

Yassine Tahraoui



Stochastic models in mechanics: theoretical and numerical aspects
Laboratoire de Mécanique & d'Acoustique, Marseille
August 31, 2023

Obstacle problems

$\partial I_K(u) \ni$

$$f - \partial_t \left(u - \int_0^\cdot G(u, \cdot) dW \right) - A(u, \cdot),$$

K : convex in some B-space

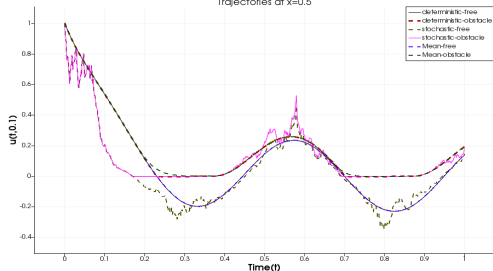
$$0 = \partial_t \left(u - \int_0^\cdot G(u, \cdot) dW \right) + A(u, \cdot) - f$$

on $\{u > \psi\}$,

$$k = \partial_t \left(u - \int_0^\cdot G(u, \cdot) dW \right) + A(u, \cdot) - f$$

on $\{u = \psi\}$.

Trajectories at $x=0.5$



(i) Formulations? Exist. + Uniq.?

(ii) Lewy-Stampacchia inequalities?

$$0 \leq -k \leq h^-$$

(iii) More on the dynamics??

- Rare events/ small noise LDP:

↪ How the stochastic perturbations effects the dynamics? $(u_\delta)_{\delta \downarrow 0}$?

$$\partial I_K(u_\delta) \ni f - \partial_t \left(u_\delta - \delta \int_0^\cdot G(u_\delta, \cdot) dW \right) - A(u_\delta, \cdot); \quad \delta > 0, t \geq 0,$$

- Invariant measures & Ergodicity?

↪ Markov semigroup properties? $t \rightarrow +\infty$?

$$\partial I_K(u) \ni f - \partial_t \left(u - \int_0^\cdot G(u) dW \right) - A(u), \quad (1)$$

(iii) More on the dynamics??

- Rare events/ small noise LDP:

↪ How the stochastic perturbations effects the dynamics? $(u_\delta)_{\delta \downarrow 0}$?

$$\partial I_K(u_\delta) \ni f - \partial_t \left(u_\delta - \delta \int_0^\cdot G(u_\delta, \cdot) dW \right) - A(u_\delta, \cdot); \quad \delta > 0, t \geq 0,$$

- Invariant measures & Ergodicity?

↪ Markov semigroup properties? $t \rightarrow +\infty$?

$$\partial I_K(u) \ni f - \partial_t \left(u - \int_0^\cdot G(u) dW \right) - A(u), \quad (1)$$

Singularities caused by the obstacle? \iff Lewy-Stampacchia inequality ✓

Large deviations

$$(X_t^\delta)' = b(X_t^\delta) + \delta \psi_t, \quad X_t^\delta(0) = x_0 \iff (x_t)' = b(x_t), \quad x_t(0) = x_0$$

Let $D \subset \mathbb{R}^d$ where $x_0 \in D$.

$x_t \in D$ for any $t \geq 0$ and attracted to equilibrium position x_* as $t \rightarrow \infty$.

\rightsquigarrow Does X_t^δ have the same property with $P \approx 1$?

Large deviations

$$(X_t^\delta)' = b(X_t^\delta) + \delta \psi_t, \quad X_t^\delta(0) = x_0 \iff (x_t)' = b(x_t), \quad x_t(0) = x_0$$

Let $D \subset \mathbb{R}^d$ where $x_0 \in D$.

$x_t \in D$ for any $t \geq 0$ and attracted to equilibrium position x_* as $t \rightarrow \infty$.

\rightsquigarrow Does X_t^δ have the same property with $P \approx 1$?

$\rightsquigarrow P(\sup_{t \in [0, \infty]} |\psi_t| < \infty) = 0 \rightarrow I = [0, \infty[= \cup_k I_T^k = \cup_k [kT, (k+1)T]$

$\rightsquigarrow \sup_{t \in I_T^k} |X_t^\delta - x_t| \leq \delta, \quad \delta \ll 1$

$\rightarrow P(X_t^\delta \notin D \text{ for some } t \in [kT, (k+1)T]) \approx \delta$

→ The behaviour of X_t^δ on I_T^k are independent $\implies X_t^\delta \notin D$.

→ The first time exit $\tau^\delta \sim \text{Exp}(\lambda)$ with

$$\lambda = \frac{1}{T} P(X_t^\delta \text{ exists from } D \text{ for } t \in I_T^k)$$

X_t^δ exists D with $P \approx \delta \iff$ the probability of improbable events $t \nearrow +\infty?$

→ The behaviour of X_t^δ on I_T^k are independent $\implies X_t^\delta \notin D$.

→ The first time exit $\tau^\delta \sim \text{Exp}(\lambda)$ with

$$\lambda = \frac{1}{T} P(X_t^\delta \text{ exists from } D \text{ for } t \in I_T^k)$$

X_t^δ exists D with $P \approx \delta \iff$ the probability of improbable events $t \nearrow +\infty?$

• Gaussian perturbations \iff asymptotics of the form $\exp(\frac{-c}{\delta^2})$, $\delta \downarrow 0$

$$P(d(X_t^\delta, \varphi) < \delta) \approx \exp\left(\frac{-1}{\delta^2} S(\varphi)\right) \quad \text{for } \delta, \delta \ll 1.$$

" φ is a smooth function"

S : rate function \iff Entropy in statistical mechanics.

Definitions

Let E be a Polish space with the Borel σ -field $\mathcal{B}(E)$.

Definition

A function $I : E \rightarrow [0, \infty]$ is called a **rate function** on E if for each $M < \infty$ the level set $\{x \in E : I(x) \leq M\}$ is a compact.

Definition

A family $\{X^\delta\}_\delta$ of E -valued random elements is said to satisfy a large deviation principle with **rate function** I if for each $G \in \mathcal{B}(E)$

$$\begin{aligned} - \inf_{x \in G^0} I(x) &\leq \liminf_{\delta \rightarrow 0} \delta^2 \log P(X^\delta \in G) \leq \limsup_{\delta \rightarrow 0} \delta^2 \log P(X^\delta \in G) \\ &\leq - \inf_{x \in \bar{G}} I(x), \end{aligned}$$

where G^0 and \bar{G} are respectively the interior and the closure of G in E .

LDP / infinite dimensional setting

- The variational representation for functionals of Wiener process and LDP \rightsquigarrow A.Budhiraja and P.Dupuis 20':
LDP and the Laplace principle, weak cv method.
- Sufficient condition to prove LDP: Matoussi, Sabbagh and Zhang 21'
 \rightsquigarrow Reflected measure, penalization, weak cv.
 \rightsquigarrow Quasilinear obstacle problems!

Notations

For $N \in \mathbb{N}$:

$$S_N = \left\{ \phi \in L^2([0, T]; H_0); \int_0^T \|\phi(s)\|_{H_0}^2 ds \leq N \right\},$$

$$\mathcal{A} = \left\{ v; v : \Omega_T \rightarrow H_0, \text{ predictable } P\left(\int_0^T \|v(s)\|_{H_0}^2 ds < \infty\right) = 1 \right\},$$

$$\mathcal{A}_N = \{v \in \mathcal{A} : v(\omega) \in S_N \text{ P-a.s.}\}.$$

$\rightsquigarrow g^\delta, g^0?$

Let $g^\delta : C([0, T], H) \rightarrow E$ be a measurable map such that $g^\delta(W(\cdot)) = X^\delta$.
Suppose that there exists a measurable map $g^0 : C([0, T], H) \rightarrow E$ s.t.

- ① For every $N < \infty$, any family $\{v^\delta : \delta > 0\} \subset \mathcal{A}_N$ and any $\epsilon > 0$,

$$\lim_{\delta \rightarrow 0} P(\rho(Y^\delta, Z^\delta) > \epsilon) = 0,$$

where $Y^\delta = g^\delta(W(\cdot) + \frac{1}{\delta} \int_0^\cdot v_s^\delta ds)$, $Z^\delta = g^0(\int_0^\cdot v_s^\delta ds)$ and $\rho(\cdot, \cdot)$ stands for the metric in the space E .

- ② For every $N < \infty$ and any family $\{v^\delta : \delta > 0\} \subset S_N$ satisfying that v_δ converges weakly to some element v as $\delta \rightarrow 0$,

$$g^0\left(\int_0^\cdot v_s^\delta ds\right) \rightarrow g^0\left(\int_0^\cdot v_s ds\right) \text{ in the space } E.$$

LDP for obstacle problems (\mathcal{P})

$D \subset \mathbb{R}^d$, $T > 0$; $V = W_0^{1,p}(D)$; $H = L^2(D)$, $(\Omega, \mathcal{F}, P; \{\mathcal{F}_t\}_{t \geq 0})$ is given.

$$\begin{cases} du_\delta + A(u_\delta, \cdot)ds + k_\delta ds = f ds + \delta G(\cdot, u_\delta)dW, \delta > 0 & \text{in } D \times \Omega_T, \\ u_\delta(t=0) = u_0 & \text{in } D, \\ u_\delta \geq \psi & \text{in } D \times \Omega_T, \\ u_\delta = 0 & \text{on } \partial D \times \Omega_T, \\ \langle k_\delta, u_\delta - \psi \rangle_{V',V} = 0 \text{ and } -k_\delta \in (V')^+ & \text{a.e. in } \Omega_T. \end{cases}$$

$\exists! X_\delta := (u_\delta, k_\delta)$. In particular, $\{X_\delta\}_\delta$ takes values in

$$(C([0, T]; H) \cap L^p(0, T; V)) \times L^{p'}(0, T; V') \quad P - a.s.$$

$(C([0, T]; H) \cap L^p(0, T; V), |\cdot|_T)$ is a Polish space with the following norm

$$|f - g|_T = \sup_{t \in [0, T]} \|f - g\|_H + \left(\int_0^T \|f - g\|_V^p ds \right)^{1/p}.$$

\rightsquigarrow Y. Tahraoui and G. Vallet: Lewy–Stampacchia’s inequality for a stochastic T-monotone obstacle problem, Stoch PDE: Anal Comp 10, 90–125 (2022).

Assumptions (LDP)

- $W(\cdot)$ is a $\{\mathcal{F}_t\}_{t \geq 0}$ -adapted Q -Wiener process in H .
- $\max(1, \frac{2d}{d+2}) < p < +\infty$.

H_1 : Let $A : V \times [0, T] \rightarrow V'$, $G : H \times [0, T] \rightarrow L_2(\overbrace{H_0}^{Q^{1/2}H}, H)$.

H_2 : A is T -monotone, coercive, hemicontinuous +growth.

H_3 : G is Lipschitz w.r.t. $u \in H$ and $\|G(0, \cdot)\|_{L_2(H_0, H)}^2 < \infty$.

H_4 : $\psi \in L^\infty(0, T; V)$, $\frac{d\psi}{dt} \in L^{p'}(0, T; V')$ and $G(\psi, \cdot) = 0$.

Assumptions (LDP)

- $W(\cdot)$ is a $\{\mathcal{F}_t\}_{t \geq 0}$ -adapted Q -Wiener process in H .
- $\max(1, \frac{2d}{d+2}) < p < +\infty$.

H_1 : Let $A : V \times [0, T] \rightarrow V'$, $G : H \times [0, T] \rightarrow L_2(\overbrace{H_0}^{Q^{1/2}H}, H)$.

H_2 : A is T -monotone, coercive, hemicontinuous +growth.

H_3 : G is Lipschitz w.r.t. $u \in H$ and $\|G(0, \cdot)\|_{L_2(H_0, H)}^2 < \infty$.

H_4 : $\psi \in L^\infty(0, T; V)$, $\frac{d\psi}{dt} \in L^{p'}(0, T; V')$ and $G(\psi, \cdot) = 0$.
 $\rightsquigarrow \max(1, \frac{2d}{d+2}) < p < 2!$


H_5 : $f \in L^\infty(0, T; V')$ s.t. $f - \partial_t \psi - A(\psi, \cdot) \in L^p(0, T; V)^*$.

H_6 : $u_0 \in H$ satisfies the constraint, i.e. $u_0 \geq \psi(0)$.

Main result

✓ the existence of a Borel-measurable map ¹

$$g^\delta : C([0, T]; H) \rightarrow C([0, T]; H) \cap L^p(0, T; V); u_\delta = g^\delta(W) \quad P - a.s.$$

¹M. Röckner, B. Schmulland and X. Zhang: Yamada-Watanabe theorem for stochastic evolution equations in infinite dimensions. *Condens. Matter Phys.* **54**, 247–259, 2008. 

Main result


✓ the existence of a Borel-measurable map ¹

$$g^\delta : C([0, T]; H) \rightarrow C([0, T]; H) \cap L^p(0, T; V); u_\delta = g^\delta(W) \quad P - a.s.$$

→ g^0 ? : Let $\phi \in L^2([0, T]; H_0)$, $\exists!(y^\phi, R^\phi)$ s.t.

$$\begin{cases} \frac{dy^\phi}{dt} + A(y^\phi, \cdot) + R^\phi = f + G(\cdot, y^\phi)\phi & \text{in } V', y^\phi(0) = u_0 \text{ in } H, \\ y^\phi \geq \psi \text{ a.e. in } D \times [0, T], \\ -R^\phi \in (V')^+ : \langle R^\phi, y^\phi - \psi \rangle_{V', V} = 0 \text{ a.e. in } [0, T]. \end{cases} \quad (2)$$

"the skeleton equations"

¹M. Röckner, B. Schmulland and X. Zhang: Yamada-Watanabe theorem for stochastic evolution equations in infinite dimensions. *Condens. Matter Phys.* **54**, 247–259, 2008. 

Definition

The pair (y^ϕ, R^ϕ) is a solution to (2) if and only if:

- $(y^\phi, R^\phi) \in (L^p(0, T; V) \cap C([0, T]; H)) \times L^{p'}(0, T; V')$, $y^\phi(0) = u_0$ and $y^\phi \geq \psi$.
- $-R^\phi \in (L^{p'}(0, T; V'))^+$ and $\int_0^T \langle R^\phi, y^\phi - \psi \rangle ds = 0$.
- For all $t \in [0, T]$,

$$\begin{aligned} (y^\phi(t), \Phi) + \int_0^t \langle R^\phi, \Phi \rangle ds + \int_0^t \langle A(y^\phi, \cdot), \Phi \rangle ds \\ = (u_0, \Phi) + \int_0^t (f + G(\cdot, y^\phi)\phi, \Phi) ds, \quad \forall \Phi \in V. \end{aligned}$$

Theorem

$\exists!(y^\phi, R^\phi)$ to (2). Moreover, the following L-S inequality holds:

$$0 \leq \frac{dy^\phi}{ds} + A(y^\phi, \cdot) - G(y^\phi, \cdot)\phi - f \leq h^- = (f - \partial_t \psi - A(\psi, \cdot))^- . \quad (3)$$

Theorem

$\exists!(y^\phi, R^\phi)$ to (2). Moreover, the following L-S inequality holds:

$$0 \leq \frac{dy^\phi}{ds} + A(y^\phi, \cdot) - G(y^\phi, \cdot)\phi - f \leq h^- = (f - \partial_t \psi - A(\psi, \cdot))^- . \quad (3)$$

✓ Define the measurable mapping g^0 as follows

$$g^0 : C([0, T]; H) \rightarrow L^p(0, T; V) \cap C([0, T]; H)$$
$$\int_0^\cdot \phi ds \mapsto g^0\left(\int_0^\cdot \phi ds\right) := y^\phi \quad \text{for } \phi \in L^2([0, T]; H_0), \quad (4)$$

where $y^\phi \in L^p(0, T; V) \cap C([0, T]; H)$ is the unique solution of (2).

Result "LDP"

Theorem

Assume H_1 - H_6 hold. Let $\{u^\delta\}_{\delta>0}$ be the unique solution of (\mathcal{P}) . Then

- 1 $\{u^\delta\}_\delta$ satisfies LDP on $C([0, T]; H)$, as $\delta \downarrow 0$, with the rate function \mathbb{I} .
- 2 If moreover H_7 holds. Then $\{u^\delta\}_\delta$ satisfies LDP on $C([0, T]; H) \cap L^p(0, T; V)$, as $\delta \downarrow 0$, with the rate function \mathbb{I} .

$$\mathbb{I}(y) = \inf_{\{\phi \in L^2([0, T], H_0)\}} \left\{ \frac{1}{2} \int_0^T \|\phi(s)\|_{H_0}^2 ds; \quad y := y^\phi = g^0\left(\int_0^\cdot \phi ds\right) \right\}.$$

$$H_7 : \exists \lambda_T \in \mathbb{R}, \exists \bar{\alpha} > 0 : \forall v_1, v_2 \in V$$

$$\langle A(v_1, \cdot) - A(v_2, \cdot), v_1 - v_2 \rangle \geq \bar{\alpha} \|v_1 - v_2\|_V^p - \lambda_T \|v_1 - v_2\|_H^2.$$

Outline of the proof

a-The Skeleton equation

$$\begin{cases} \frac{dy^\phi}{dt} + A(y^\phi, \cdot) + R^\phi = f + G(\cdot, y^\phi)\phi & \text{in } V', y^\phi(0) = u_0 \text{ in } H, \\ y^\phi \geq \psi \text{ a.e. in } & D \times [0, T], \\ -R^\phi \in (V')^+ : \langle R^\phi, y^\phi - \psi \rangle_{V', V} = 0 & \text{a.e. in } [0, T]. \end{cases}$$

- Uniqueness \iff monotonicity + Lipschitz multiplicative noise.
- Existence & L-S inequalities: Regular data \rightarrow general data
✓ Talk by Guy Vallet at 14:00

Outline of the proof

a-The Skeleton equation

$$\begin{cases} \frac{dy^\phi}{dt} + A(y^\phi, \cdot) + R^\phi = f + G(\cdot, y^\phi)\phi & \text{in } V', y^\phi(0) = u_0 \text{ in } H, \\ y^\phi \geq \psi \text{ a.e. in } & D \times [0, T], \\ -R^\phi \in (V')^+ : \langle R^\phi, y^\phi - \psi \rangle_{V', V} = 0 & \text{a.e. in } [0, T]. \end{cases}$$

- Uniqueness \iff monotonicity + Lipschitz multiplicative noise.
- Existence & L-S inequalities: Regular data \rightarrow general data
✓ Talk by Guy Vallet at 14:00
- $\max(1, \frac{2d}{d+2}) < p < 2 \iff G(\cdot, y^\phi)\phi \iff L^\infty(\cdot; \cdot)$ in $H_4 + H_5!$

b- Continuity of skeleton equations

Let $\{v^\delta : \delta > 0\} \subset S_N$ satisfying that $v_\delta \rightarrow v$ as $\delta \rightarrow 0$. Then

- $g^0(\int_0^\cdot v_s^\delta ds)$ converges to $g^0(\int_0^\cdot v_s ds)$ in the space $C([0, T]; H)$,
- If moreover H_7 holds, then

$$g^0(\int_0^\cdot v_s^\delta ds) \rightarrow g^0(\int_0^\cdot v_s ds) \text{ in } L^p(0, T; V) \cap C([0, T]; H).$$

Let $(\phi_n)_n \subset S_N$ such that $\phi_n \rightarrow \phi$ in $L^2(0, T; H_0)$.

$$y_n \rightarrow y^\phi \text{ in } L^p(0, T; V) \cap C([0, T]; H)?$$

y_n and y^ϕ resp. are the solutions of (2) corresponding to ϕ_n and ϕ resp.

- A priori estimates \iff L-S inequalities ✓
- Convergence of $y_{n_k} \rightarrow y$ in $L^2(0, T; H)$ \iff Compactness ✓
- Boundedness of (ϕ_n) & weak cv+ strong cv $y_n \rightarrow y$ in $L^2(0, T; H)$.
- Monotonicity \implies convergence of y_{n_k} to \tilde{y} .
- cv of y_n and $\tilde{y} = y^\phi \iff$ Uniqueness ✓

c- vanishing multiplicative noise $\delta \downarrow 0$

Assume $H_1 - H_6$. Let $\{\phi^\delta : \delta > 0\} \subset \mathcal{A}_N$ for some $N < \infty$. Then

$$\lim_{\delta \rightarrow 0} P\left(\sup_{t \in [0, T]} \|(v_\delta - u_\delta)(t)\|_H > \epsilon\right) = 0, \quad \forall \epsilon > 0.$$

Moreover, if H_7 holds, then $\lim_{\delta \rightarrow 0} P(|v_\delta - u_\delta|_T > \epsilon) = 0, \quad \forall \epsilon > 0.$

$$v_\delta = g^\delta(W(\cdot) + \frac{1}{\delta} \int_0^\cdot \phi^\delta(s) ds) = g^\delta(W^\delta(\cdot)),$$
$$u_\delta = g^0(\phi^\delta).$$

Let $\{\phi^\delta\}_{\delta>0} \subset \mathcal{A}_N$ for some $N < \infty$.

- Girsanov theorem $\implies \exists Q$ -Wiener process W^δ , with respect to $\{\mathcal{F}_t\}_{t \geq 0}$ on $(\Omega, \mathcal{F}, P^\delta)$ where

$$W^\delta(t) = W(t) + \frac{1}{\delta} \int_0^t \phi^\delta(s) ds, \quad t \in [0, T] \text{ and}$$

$$dP^\delta = \exp\left[-\frac{1}{\delta} \int_0^T \langle \phi^\delta(s), dW(s) \rangle_{H_0} - \frac{1}{2\delta^2} \int_0^T \|\phi^\delta(s)\|_{H_0}^2 ds\right] dP. \quad (5)$$

$$\rightsquigarrow \nu_\delta = g^\delta(W(\cdot) + \frac{1}{\delta} \int_0^\cdot \phi^\delta(s) ds) = g^\delta(W^\delta(\cdot)).$$

Let $\{\phi^\delta\}_{\delta>0} \subset \mathcal{A}_N$ for some $N < \infty$.

- Girsanov theorem $\implies \exists$ Q -Wiener process W^δ , with respect to $\{\mathcal{F}_t\}_{t \geq 0}$ on $(\Omega, \mathcal{F}, P^\delta)$ where

$$W^\delta(t) = W(t) + \frac{1}{\delta} \int_0^t \phi^\delta(s) ds, \quad t \in [0, T] \text{ and}$$

$$dP^\delta = \exp\left[-\frac{1}{\delta} \int_0^T \langle \phi^\delta(s), dW(s) \rangle_{H_0} - \frac{1}{2\delta^2} \int_0^T \|\phi^\delta(s)\|_{H_0}^2 ds\right] dP. \quad (5)$$

$$\rightsquigarrow v_\delta = g^\delta(W(\cdot) + \frac{1}{\delta} \int_0^\cdot \phi^\delta(s) ds) = g^\delta(W^\delta(\cdot)).$$

- Uniform estimates for (v_δ) and (u_δ) : ψ is "deterministic"!
 - L -S not preserved $\iff P^\delta!$
- Conclusion.

Invariant measures

- Markovian process
- $\lim_{t \rightarrow \infty} P_t^* \delta_{u_0}$ for given transition probability (semigroup) P_t ?
- Convergence to equilibrium? (strongly mixing, Exponential \dots).
- Ergodicity: for any $\varphi \in L^2(H, \mu)$

"Temporal" average of $P_t \varphi$ coincides with the "spatial" average of φ .

Invariant measures ($T \rightarrow +\infty$)

$$\left\{ \begin{array}{ll} du + A(u)ds + kds = fds + G(u)dW & \text{in } D \times \Omega_T, \\ u(t=0) = u_0 \text{ in } D; \quad u \geq \psi & \text{in } D \times \Omega_T, \\ u = 0 & \text{on } \partial D \times \Omega_T, \\ \langle k, u - \psi \rangle_{V',V} = 0 \text{ and } -k \in (V')^+ & \text{a.e. in } \Omega_T, \end{array} \right. \quad (6)$$

- $A : V \rightarrow V'$ and $G : H \rightarrow L_2(H_0, H)$ are measurable.
- A is T -monotone, coercive, hemicontinuous + growth.
- $\forall \theta, \sigma \in H: \|G(\theta) - G(\sigma)\|_{L_2(H_0, H)}^2 \leq L_G \|\theta - \sigma\|_H^2$;
 $\|G(0, \cdot)\|_{L_2(H_0, H)}^2 < \infty$.
- $\psi \in V$ and $G(\psi) = 0$, $f \in V'$ such that $f - A(\psi) = h \in V^*$.
- $u_0 \in H$ satisfies the constraint, i.e. $u_0 \geq \psi$.

Theorem

$\exists!(u, k)$ to (6). Moreover, the following L-S inequality holds

$$0 \leq \partial_t \left(u - \int_0^{\cdot} G(u) dW \right) + A(u) - f = -k \leq h^- = (f - A(\psi))^- . \quad (7)$$

Theorem

$\exists!(u, k)$ to (6). Moreover, the following L-S inequality holds

$$0 \leq \partial_t \left(u - \int_0^{\cdot} G(u) dW \right) + A(u) - f = -k \leq h^- = (f - A(\psi))^- . \quad (7)$$

\rightsquigarrow Let $\epsilon > 0$ and consider the following approximating problem:

$$\begin{cases} u_\epsilon(t) + \int_0^t (A(u_\epsilon) - \frac{1}{\epsilon} [(u_\epsilon - \psi)^-]^{\tilde{q}-1} - f) ds = u_0 + \int_0^t \tilde{G}(u_\epsilon) dW(s) \\ u_0 \geq \psi, \end{cases} \quad (8)$$

where $\tilde{q} = \min(p, 2)$ and $\tilde{G}(u_\epsilon) = G(\max(u_\epsilon, \psi))$.

\rightsquigarrow Let u_ϵ and u , respectively are the unique solution of (8) and (6):

$$E \sup_{t \in [0, T]} \|(u_\epsilon - u)(t)\|_H^2 \leq C\epsilon \quad \text{for all } \epsilon > 0, \quad (9)$$

Markov semigroup

Let $\epsilon > 0$ and $u_\epsilon(t, s; \xi)$, $t \geq s \geq 0$ be the unique strong solution to (8) starting at time s from an \mathcal{F}_s -measurable initial data $\xi \in H$. Let $T > 0$,

$$\mathbb{E} \|u_\epsilon(t, s; \xi) - u_\epsilon(t, s; \theta)\|_H^2 \leq e^{[L_G + 2\lambda](t-s)} \mathbb{E} \|\xi - \theta\|_H^2 \quad \forall 0 \leq s \leq t \leq T.$$

- $\mathcal{C}_b(H)$: the set of bounded continuous function from H to \mathbb{R} .

$$P_t^\epsilon \varphi : H \rightarrow \mathbb{R}; \quad (P_t^\epsilon \varphi)(\xi) := \mathbb{E}[\varphi(u_\epsilon(t; \xi))], \quad \xi \in H, \varphi \in \mathcal{C}_b(H),$$

where $u_\epsilon(t; \xi)$, $t \geq 0$ is the unique strong solution to (8), $\xi \in H$.

Markov semigroup

Let $\epsilon > 0$ and $u_\epsilon(t, s; \xi)$, $t \geq s \geq 0$ be the unique strong solution to (8) starting at time s from an \mathcal{F}_s -measurable initial data $\xi \in H$. Let $T > 0$,

$$\mathbb{E} \|u_\epsilon(t, s; \xi) - u_\epsilon(t, s; \theta)\|_H^2 \leq e^{[L_G + 2\lambda](t-s)} \mathbb{E} \|\xi - \theta\|_H^2 \quad \forall 0 \leq s \leq t \leq T.$$

- $\mathcal{C}_b(H)$: the set of bounded continuous function from H to \mathbb{R} .

$$P_t^\epsilon \varphi : H \rightarrow \mathbb{R}; \quad (P_t^\epsilon \varphi)(\xi) := \mathbb{E}[\varphi(u_\epsilon(t; \xi))], \quad \xi \in H, \varphi \in \mathcal{C}_b(H),$$

where $u_\epsilon(t; \xi)$, $t \geq 0$ is the unique strong solution to (8), $\xi \in H$.

- Standard arguments \implies

$$P_{s,t}^\epsilon = P_{0,t-s}^\epsilon \quad \forall 0 \leq s \leq t < \infty \text{ and } P_t^\epsilon := P_{0,t}^\epsilon,$$

$$\mathbb{E}[\varphi(u_\epsilon(t+s; \eta)) | \mathcal{F}_t] = (P_s^\epsilon \varphi)(u_\epsilon(t; \eta)) \quad \forall \varphi \in \mathcal{C}_b(H), \forall \eta \in H, \forall t, s > 0,$$

- Denote by $P_{s,t}^\epsilon \varphi(\xi) := \mathbb{E}[\varphi(u_\epsilon(t, s; \xi))]$, $\xi \in H$.

$$(P_{t+s}^\epsilon \varphi)(\eta) = (P_t^\epsilon (P_s^\epsilon \varphi))(\eta) \quad \forall \varphi \in \mathcal{C}_b(H), \forall \eta \in H, \forall t, s > 0.$$

Solution of (8) defines a homogeneous Feller–Markov process.

- Denote by $P_{s,t}^\epsilon(\xi) := \mathbb{E}[\varphi(u_\epsilon(t, s; \xi))]$, $\xi \in H$.

$$(P_{t+s}^\epsilon \varphi)(\eta) = (P_t^\epsilon(P_s^\epsilon \varphi))(\eta) \quad \forall \varphi \in \mathcal{C}_b(H), \forall \eta \in H, \forall t, s > 0.$$

Solution of (8) defines a homogeneous Feller–Markov process.

$$K_\psi = \{h \in H, \quad h \geq \psi\}$$

- Let $\eta \in K_\psi$ and $u(t; \eta) \in K_\psi, t \geq 0$ be the unique strong solution to (6).


$$\mathbb{E}\|u(t, s; \xi) - u(t, s; \theta)\|_H^2 \leq e^{[L_G + 2\lambda_T](t-s)} \mathbb{E}\|\xi - \theta\|_H^2 \quad \forall 0 \leq s \leq t \leq T,$$

$[u(t, s; \xi)]_{t \geq s \geq 0}$ is the unique strong solution to (6) with $u(s) = \xi \in K_\psi$.

Semigroup for the obstacle problem

$\rightsquigarrow u(t; \eta), t \geq 0$ be the unique strong solution to (6) starting from $\eta \in K_\psi$.

$$P_t \varphi : K_\psi \rightarrow \mathbb{R}; \quad (P_t \varphi)(\eta) := \mathbb{E}[\varphi(u(t; \eta))], \quad \eta \in K_\psi \quad \forall \varphi \in C_b(H).$$

²L. Zambotti. *A reflected stochastic heat equation as symmetric dynamics with respect to the 3-d Bessel bridge*. JFA, 180(1), 195-209, 2001. 

Semigroup for the obstacle problem

$\rightsquigarrow u(t; \eta), t \geq 0$ be the unique strong solution to (6) starting from $\eta \in K_\psi$.

$$P_t \varphi : K_\psi \rightarrow \mathbb{R}; \quad (P_t \varphi)(\eta) := \mathbb{E}[\varphi(u(t; \eta))], \quad \eta \in K_\psi \quad \forall \varphi \in \mathcal{C}_b(H).$$


Lemma

$(P_t)_t$ is bounded on $\mathcal{C}_b(H)$, **Markov-Feller** and stochastically continuous semigroup on $\mathcal{C}_b(K_\psi)$. Moreover, for $\varphi \in \mathcal{C}_b(H), \eta \in K_\psi$, and $t, s \geq 0$:

$$\lim_{\epsilon \rightarrow 0} (P_t^\epsilon \varphi)(\eta) = (P_t \varphi)(\eta), \quad (P_{t+s} \varphi)(\eta) = (P_t (P_s \varphi))(\eta)$$

$$P_{t+s,t} = P_{s,0}, \quad P_{t,s} \varphi(\eta) := \mathbb{E}[\varphi(u(t, s; \eta))] \text{ for } 0 \leq s \leq t < \infty, \quad P_t := P_{0,t}.$$

- Convergence in law for u_ϵ , cv of $(P_t^\epsilon)_\epsilon$ and [Lemma 1]².

²L. Zambotti. A reflected stochastic heat equation as symmetric dynamics with respect to the 3-d Bessel bridge. JFA, 180(1), 195-209, 2001. 

Definition

Let $(P_t)_t$ be a Markov semigroup on H .

- a probability measure ν is said to be invariant for P_t if:

$$\int_H P_t \varphi d\nu = \int_H \varphi d\nu, \quad \forall \varphi \in B_b(H) \text{ and } t \geq 0.$$

- Let ν be an invariant measure for P_t , ν is ergodic if:

$$\lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T P_t \varphi dt = \int_H \varphi(x) \mu(dx), \quad \forall \varphi \in L^2(H, \mu).$$

- P_t is strongly mixing if: $\lim_{t \rightarrow +\infty} P_t \varphi(x) = \int_H \varphi(x) \mu(dx)$ in $L^2(H, \mu)$.

Theorem

Under the above assumptions H_1 - H_6 :

- 1 There exists *an ergodic* invariant measure μ for $(P_t)_t$ if $p > 2$.
- 2 Assuming $p = 2$ and there exists $\bar{\alpha} > 0$ such that

$$(1 - \delta)\alpha - C_D \left[\lambda + \frac{L_G(1 + K^2)}{2K^2} \right]^+ \geq \bar{\alpha} \text{ for some } \delta \in]0, 1[, \forall K > 0$$

then there exists *an ergodic* invariant measure μ for $(P_t)_t$.

Moreover, μ is concentrated in V satisfying $\int_H \|x\|_V^p \mu(dx) < +\infty$.

$$C_D > 0: \quad \|u\|_H^2 \leq C_D \|u\|_V^2, \quad \forall u \in V,$$

Theorem

Under the above assumptions H_1 - H_6 :

- 1 There exists *an ergodic* invariant measure μ for $(P_t)_t$ if $p > 2$.
- 2 Assuming $p = 2$ and there exists $\bar{\alpha} > 0$ such that

$$(1 - \delta)\alpha - C_D \left[\lambda + \frac{L_G(1 + K^2)}{2K^2} \right]^+ \geq \bar{\alpha} \text{ for some } \delta \in]0, 1[, \forall K > 0$$

then there exists *an ergodic* invariant measure μ for $(P_t)_t$.

Moreover, μ is concentrated in V satisfying $\int_H \|x\|_V^p \mu(dx) < +\infty$.

$$C_D > 0: \quad \|u\|_H^2 \leq C_D \|u\|_V^2, \quad \forall u \in V,$$

Assuming $\max(1, \frac{2d}{d+2}) < p < 2$ and $\lambda + \frac{L_G(1 + K^2)}{2K^2} \leq 0$. Then there exists an invariant measure μ for $(P_t)_t$!

The set $\{\nu_n := \frac{1}{t_n} \int_0^{t_n} \mu_s^\eta ds; n \in \mathbb{N}^*\}$ is tight on H .

μ_s^η is the law of $u(s; \eta)$

$$\frac{1}{2} \mathbb{E} \|u(t)\|_H^2 + (1 - \delta) \alpha \int_0^t \mathbb{E} \|u\|_V^p ds \leq \frac{1}{2} \|\eta\|_H^2 + C(p, f, \psi, L_G) t$$
$$(K > 0) + \left[\lambda + \frac{L_G(1 + K^2)}{2K^2} \right] \int_0^t \mathbb{E} \|u\|_H^2 ds.$$

The set $\{\nu_n := \frac{1}{t_n} \int_0^{t_n} \mu_s^\eta ds; n \in \mathbb{N}^*\}$ is tight on H .

μ_s^η is the law of $u(s; \eta)$

$$\frac{1}{2} \mathbb{E} \|u(t)\|_H^2 + (1 - \delta) \alpha \int_0^t \mathbb{E} \|u\|_V^p ds \leq \frac{1}{2} \|\eta\|_H^2 + C(p, f, \psi, L_G) t$$
$$(K > 0) + \left[\lambda + \frac{L_G(1 + K^2)}{2K^2} \right] \int_0^t \mathbb{E} \|u\|_H^2 ds.$$

Let $B_R := \{v \in V : \|v\|_V \leq R\}; R \in \mathbb{N}$. Let $t_n > 0, R > 0$.

$$\nu_n(B_R^c) = \frac{1}{t_n} \int_0^{t_n} P(\|u(s; \eta)\|_V > R) ds \leq \frac{1}{t_n R^p} \int_0^{t_n} \mathbb{E} \|u(s; \eta)\|_V^p ds.$$

\rightsquigarrow "Krylov–Bogolyubov method" \implies Exist. of an invariant measure \checkmark

The set $\{\nu_n := \frac{1}{t_n} \int_0^{t_n} \mu_s^\eta ds; n \in \mathbb{N}^*\}$ is tight on H .

μ_s^η is the law of $u(s; \eta)$

$$\frac{1}{2} \mathbb{E} \|u(t)\|_H^2 + (1 - \delta) \alpha \int_0^t \mathbb{E} \|u\|_V^p ds \leq \frac{1}{2} \|\eta\|_H^2 + C(p, f, \psi, L_G) t$$

$$(K > 0) + \left[\lambda + \frac{L_G(1 + K^2)}{2K^2} \right] \int_0^t \mathbb{E} \|u\|_H^2 ds.$$

Let $B_R := \{v \in V : \|v\|_V \leq R\}; R \in \mathbb{N}$. Let $t_n > 0, R > 0$.

$$\nu_n(B_R^c) = \frac{1}{t_n} \int_0^{t_n} P(\|u(s; \eta)\|_V > R) ds \leq \frac{1}{t_n R^p} \int_0^{t_n} \mathbb{E} \|u(s; \eta)\|_V^p ds.$$

\rightsquigarrow "Krylov–Bogolyubov method" \implies Exist. of an invariant measure \checkmark

$$\nu_n \rightarrow \mu \implies \int_H \|x\|_V^p \mu(dx) < +\infty \implies \mu \text{ is ergodic.}$$

"Krein–Milman theorem".

Theorem

Assume moreover that $\frac{L_G}{2} + \lambda_T < 0$, then there exists a **unique ergodic and strongly mixing invariant measure** μ and the following convergence to equilibrium holds.

$$\left| P_t \varphi(x) - \int_H \varphi(y) \mu(dy) \right| \leq C \|\varphi\|_{1,\infty} e^{[\frac{L_G}{2} + \lambda_T]t}, \quad \forall \varphi \in C_b^1(H). \quad (10)$$

- ↪ Difference of two ergodic invariant measures.
- ↪ Continuity of P_t w.r.t. initial data.

Theorem

Assume moreover that $\frac{L_G}{2} + \lambda_T < 0$, then there exists a **unique ergodic and strongly mixing invariant measure** μ and the following convergence to equilibrium holds.

$$\left| P_t \varphi(x) - \int_H \varphi(y) \mu(dy) \right| \leq C \|\varphi\|_{1,\infty} e^{[\frac{L_G}{2} + \lambda_T]t}, \quad \forall \varphi \in C_b^1(H). \quad (10)$$

↪ Difference of two ergodic invariant measures.

↪ Continuity of P_t w.r.t. initial data.

$$\begin{aligned} du - [\operatorname{div}(|\nabla u|^{p-2} \nabla u) - u] dt + k 1_{\{u=0\}} dt &= f dt + u d\beta_t, \quad u \geq 0; \\ u_0 \in (L^2(D))^+, -f \in (L^2(D))^+ & \quad (p \geq 2) \end{aligned}$$

Comments

- Condition on $L_G \iff$ multiplicative noise.
- $G(\psi) = 0 \iff$ dual order assumption.
- LDP via standard method \iff Reflected measure?

Comments

- Condition on $L_G \iff$ multiplicative noise.
- $G(\psi) = 0 \iff$ dual order assumption.
- LDP via standard method \iff Reflected measure?
- $\max(1, \frac{2d}{d+2}) < p < 2 \iff$ Local monotone obstacle problem!
 \rightsquigarrow Example? Only additive noise but...!

Comments

- Condition on $L_G \iff$ multiplicative noise.
- $G(\psi) = 0 \iff$ dual order assumption.
- LDP via standard method \iff Reflected measure?
- $\max(1, \frac{2d}{d+2}) < p < 2 \iff$ Local monotone obstacle problem!
 \rightsquigarrow Example? Only additive noise but...!
- Obstacle nonlinear problem with rough forcing e.g. $W(t)$? \rightsquigarrow Open!
- Additive noise & invariant measures.

Thank you for your attention!



Yassine Tahraoui: Large deviations for an obstacle problem with T-monotone operator and multiplicative noise. (2023)

available on arXiv: <https://arxiv.org/abs/2308.02206>



—: Invariant measures and ergodicity for T-monotone problems with constraint and multiplicative noise. "preprint"