Explicit Euler scheme: a new way of proof for the existence of solutions for singular parabolic SPDEs

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Modèles stochastiques appliqués à la mécanique : aspects théoriques et numériques



French National Research Agency Project - SIMALIN

September 1st, 2023



Singular model of equations

- Numerical simulations
- SDE Weak solutions

2 Sewing approach and Tamed Euler scheme

- Sewing approach
- Tamed Euler scheme
- Strong existence and uniqueness of the SDE



- Finite differences
- Controlling the error

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SPDE with regular drift

Consider the stochastic reaction-diffusion

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + \frac{b}{u(t,x)} + \xi \qquad (\star)$$

where ξ is a space-time white noise and *b* is a (one-sided) Lipschitz function, i.e. polynomial-like function with negative sign of leading coefficient.

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where ξ is a space-time white noise and b is a (one-sided) Lipschitz function, i.e. polynomial-like function with negative sign of leading coefficient.

The existence and uniqueness of solutions are quite well-understood, but these results do not cover the natural cases of discontinuous drifts or reflected diffusions which are expected in physical models.

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SPDE with singular drift

Consider again the stochastic reaction-diffusion

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + \frac{b}{b}(u(t,x)) + \xi \qquad (\star)$$

where ξ is a space-time white noise, but where **b** is a generalized function in

Besov space $\mathcal{B}_{p,\infty}^{\gamma}(\mathbb{R}^d)$.

In dimension d = 1, Athreya, Butkovsky, Lê, Mytnik [ABLM21] proved that there exists a unique strong solution whenever b has some Hölder regularity (precisely Besov regularity $\gamma - 1/p \ge -1$, $\gamma > -1$ and $p \in [1, \infty]$).

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SPDE with singular drift

We can treat the following case

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + k \mathbf{1}_{u=0}(u(t,x)) + W_t$$

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$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + k \mathbf{1}_{u=0}(u(t,x)) + W_t$$

So a new way of proof for SPDE with singular drift, reflection, penalization. Furthermore, without monotonic behavior, or (one-sided) Lipschitz condition.

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Euler scheme

For the SPDE

$$dX_t = AX_t dt + \mathbf{b}(X_t) dt + dW_t$$

consider the Euler scheme with time step h = T/N

$$X^{n+1} = X^n + A(X^n)h + b(X^n)h + \Delta W^{n+1}$$

then the strong order is given by

$$\mathbb{E}\left[\sup_{0\leq n\leq N}\|X_{nh}-X^n\|^2\right]\leq C_Th.$$

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Euler scheme: rate of convergence

$$\mathbb{E}\left[\sup_{0\leq n\leq N}\|X_{nh}-X^n\|^2\right]\leq C_Th.$$

The usual way of proof is to obtain the bound of moments

$$\mathbb{E}\left[\sup_{0\leq n\leq N}\|X^n\|^p\right]\leq C_{\mathcal{T}},$$

and it is expected that the order of convergence is given by the time regularity of the noise based on the control of

$$\mathbb{E}\left[\sup_{0\leq t,s\leq T,|t-s|< h} \|W_t - W_s\|^2\right] \leq C_T h \qquad \mathbb{E}\left[\sup_{0\leq t\leq T} \|W_t\|^p\right] \leq C_T,$$

There are many way to obtain the same regularity/moment bounds for the Euler scheme, but it NEEDS an implicit treatment of the differential operator (see also exponential scheme, splitting, etc.). Otherwise it has been shown that the forward/explicit Euler scheme may not be convergent (for instance with superlinear growing of b).

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Bounded drift

Consider

$$\begin{split} \mathrm{d} X_t &= \ \mathbb{1}_{\{X_t>0\}} \mathrm{d} t + \mathrm{d} B_t^H, \\ \mathrm{d} X_t &= \ \mathbb{1}_D^{(d)}(X_t) \mathrm{d} t + \mathrm{d} B_t^H. \end{split}$$

Then $b \in \mathcal{C}^{0-}/\mathcal{B}_\infty^0$ leads to $b^n(x) = \sqrt{\frac{n}{2\pi}} \int_0^x e^{-\frac{ny^2}{2}} \mathrm{d} y$ and $n = \lfloor h^{-1} \rfloor.$

Dirac drift

Consider

$$\mathrm{d}X_t = \delta_0(X_t)\mathrm{d}t + dB_t^H.$$

Then
$$b \in \mathcal{C}^{-1-}/\mathcal{B}_p^{-d+\frac{d}{p}}$$
 leads to $b^n(x) = \sqrt{\frac{n}{2\pi}}e^{-\frac{nx^2}{2}}$ and $n = \lfloor h^{-\frac{1}{1+d}} \rfloor$.

Set $h = 2^{-7} 10^{-4}$ as reference value.

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Indicator function in dimension 1 - exact algorithm



Figure: It works!

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Indicator function in dimension 1 - tamed algorithm



Figure: It works quite well...

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Dirac distribution in dimension 1 - naive algorithm



Figure: It does not work!

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Dirac distribution in dimension - tamed algorithm



Figure: It works quite well...

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Indicator function in dimension 1



Figure: Approximate slope is 0.5

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Indicator function in dimension 2



Figure: Approximate slope is 0.5

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Dirac δ function in dimension 1



Figure: Approximate slope is 0.25

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We study the equation

$$dX_t = \mathbf{b}(X_t)dt + dB_t^H,$$

when b is a distribution in some Hölder/Besov space and B^{H} is a fractional Brownian motion.

We look for solutions of the form

$$X_t = X_0 + K_t + B_t^H,$$

where in case **b** is regular enough, $K_t = \int_0^t b(X_s) ds$.

⊮-fBm

For a filtration \mathbb{F} , we say that B^H is an \mathbb{F} -fBm if there exists an \mathbb{F} -Brownian motion W s.t. $B_t^H = \int_0^t K_H(t,s) \, dW_s$.

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Tamed Euler scheme for SPDE

Weak solutions

$$X_t = X_0 + \int_0^t \frac{b(X_s) \, ds}{s} + B_t^H, \quad t \in [0, T]. \tag{(*)}$$

Definition

 $((X_t)_{t \in [0,T]}, (B_t)_{t \in [0,T]})$ defined on some filtered probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ is a weak solution of (*) if

- B^H is an 𝔽-fBm;
- X is adapted to F;
- $\exists (K_t)_{t \in [0,T]}$ such that, a.s.,

$$X_t = X_0 + K_t + B_t^H, \quad \forall t \in [0, T];$$

• $\forall (b^k)_{k \in \mathbb{N}}$ smooth bounded functions converging to $\frac{b}{b}$ in $\mathcal{C}^{\alpha}/\mathcal{B}_p^{\gamma-}$,

$$\sup_{t\in[0,T]}\left|\int_0^t b^k(X_r)dr-K_t\right|\underset{k\to+\infty}{\xrightarrow{\mathbb{P}}} 0.$$

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Consider b is a generalized function in

Besov space $\mathcal{B}^{\gamma}_{p,\infty}(\mathbb{R}^d)$.

Numerical simulations SDE Weak solutions

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A few properties:

• $\mathcal{B}^{\gamma}_{p,\infty}(\mathbb{R}^d) \hookrightarrow \mathcal{C}^{\gamma-d/p}(\mathbb{R}^d)$ $(\gamma - d/p \text{ is the "regularity" of the space});$ You can think: $\alpha = \gamma - d/p$ is the Hölder regularity.

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- For $\gamma d/p = 0$, the space $\mathcal{B}_{p,\infty}^{\gamma}(\mathbb{R}^d)$ contains bounded functions;

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- For $\gamma d/p = 0$, the space $\mathcal{B}^{\gamma}_{p,\infty}(\mathbb{R}^d)$ contains bounded functions;
- $1_{\mathbb{R}_+} \in \mathcal{B}^0_{\infty,\infty}(\mathbb{R}^1).$

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- For $\gamma d/p < 0$, the space $\mathcal{B}^{\gamma}_{p,\infty}(\mathbb{R}^d)$ contains genuine distributions;

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- $\mathcal{B}_{p,\infty}^{\gamma}(\mathbb{R}^d) \hookrightarrow \mathcal{C}^{\gamma-d/p}(\mathbb{R}^d)$ $(\gamma d/p \text{ is the "regularity" of the space});$ You can think: $\alpha = \gamma - d/p$ is the Hölder regularity.
- For $\gamma d/p = 0$, the space $\mathcal{B}_{p,\infty}^{\gamma}(\mathbb{R}^d)$ contains bounded functions;
- $1_{\mathbb{R}_+} \in \mathcal{B}^0_{\infty,\infty}(\mathbb{R}^1).$
- For $\gamma d/p < 0$, the space $\mathcal{B}^{\gamma}_{p,\infty}(\mathbb{R}^d)$ contains genuine distributions;
- $\delta_0 \in \mathcal{B}^0_{1,\infty}(\mathbb{R})$ (or $\mathcal{B}^{-d+\frac{d}{p}}_{p,\infty}(\mathbb{R}^d)$ in dimension d).

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Weak and strong existence

Theorem ([Anzeletti-Richard-Tanré '21], [G.-Haress-Richard.'22])

Let $\gamma \in \mathbb{R}$, $p \in [1, \infty]$, $\mathbf{b} \in \mathcal{C}^{\alpha}/\mathcal{B}_{p}^{\gamma}$. [weak] Assume that

$$\alpha = \gamma - \frac{d}{p} > \frac{1}{2} - \frac{1}{2H}.$$

Then there exists a weak solution X s.t. $X - B^H \in C^{\kappa}_{[0,T]}(L^m)$, for all $m \ge 2$,

$$\forall \kappa \in (0, 1 + H\alpha] \setminus \{1\}, \qquad \forall \kappa \in \left(0, 1 + H\left(\gamma - \frac{d}{p}\right)\right] \setminus \{1\}.$$

[strong] Assume that

$$H < rac{1}{2}, \ \gamma - rac{d}{p} < 0 \ \text{and} \ \gamma - rac{d}{p} > 1 - rac{1}{2H}.$$

Then there exists a strong solution X to (*) such that $X - B \in C_{[0,T]}^{\frac{1}{2}+H}(L^m)$ for any $m \ge 2$. Besides, pathwise uniqueness holds in the class of all solutions X such that $X - B \in C_{[0,T]}^{\frac{1}{2}+H}(L^2)$.

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Reflection?

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Example

If $b = \delta_0$ ($b \in C^{-1}/B_1^0$) and d = 1, one must choose $H < \frac{1}{3}$.

Then $X - B^H$ has Hölder regularity 1 - H (> H), hence X is not reflected.

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SPDE with singular drift

We conclude the introduction by commenting on the needs to treat SDE first.

It is known that for each fixed space point, the free stochastic heat equation (that is, equation (\star) with b = 0) behaves "qualitatively" like a fractional Brownian motion (fBM) with the Hurst parameter H = 1/4.

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It is known that for each fixed space point, the free stochastic heat equation (that is, equation (*) with b = 0) behaves "qualitatively" like a fractional Brownian motion (fBM) with the Hurst parameter H = 1/4.

Indeed, the solution of

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + \dot{W}(t,x)$$

is given by the well-known stochastic convolution

$$Z(t,x) = e^{\frac{t}{2}\Delta} u_0(x) + \int_0^t e^{\frac{t-s}{2}\Delta} \mathrm{d}W(s,x)$$

which has regularity $\mathcal{C}^{\frac{1}{4}-}$ in time and $\mathcal{C}^{\frac{1}{2}-}$ in space.

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SPDE with singular drift towards SDE with fractional noise

To solve

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + \frac{b}{b}(u(t,x)) + \dot{W}(t,x). \tag{(*)}$$

Denote Y(t,x) = u(t,x) - Z(t,x), then the previous remark leads to solve

$$\partial_t (u(t,x) - Z(t,x)) = \frac{1}{2} \partial_{xx}^2 (u(t,x) - Z(t,x)) + \frac{b(u(t,x) - Z(t,x))}{b(u(t,x) - Z(t,x))} + \frac{b(u(t,x) - Z(t,x))}{b(u(t,x) - Z(t,x))}$$

a random PDE with $\mathcal{C}^{\frac{1}{4}-}$ regularity in translation.

Numerical simulations SDE Weak solutions

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$$\partial_t Y(t,x) = \frac{1}{2} \partial_{xx}^2 Y(t,x) + \frac{b}{b} (Y(t,x) + Z(t,x))$$

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Numerical simulations SDE Weak solutions

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Therefore, one can expect that strong existence and uniqueness for equation (\star) would hold under the same conditions on *b* as needed in a SDE driven by $\frac{1}{4}$ -fractional Brownian motion.
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That is $\mathbf{b} \in \mathcal{C}^{\alpha}/\mathcal{B}_{p}^{\gamma}$, where $\alpha = \gamma - 1/p > -1$. Note that the Dirac delta function lies in $\mathcal{B}_{p}^{-1+1/p}$ which is the critical case.

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0.8 0.6 0.4 0.2 0 -0.2 L 0.5 0.1 0.2 0.3 0.4 0.6 0.7 0.8 0.9 1

Figure: Breaks physical limit

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0.8 0.6 0.4 0.2 0 -0.2 0.5 0.1 0.2 0.3 0.4 0.6 0.7 0.8 0.9 1

Figure: Penalization steps

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Figure: Leaves physical limit

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Elements of proof: The basic ingredient is the *stochastic* sewing lemma.

Lemma ([Lê'20])

Let $m \in [2, \infty)$. Let $A : \Delta_{0,1} \to L^m(\Omega)$ s.t. $A_{s,t}$ is \mathcal{F}_t -measurable. Assume $\exists \Gamma_1, \Gamma_2 \geq 0$, and $\varepsilon_1, \varepsilon_2 > 0$ s.t. $\forall (s, t) \in \Delta_{0,1}$ and $u := \frac{s+t}{2}$,

$$\begin{split} \|\mathbb{E}^{s}[\delta A_{s,u,t}]\|_{L^{m}} &\leq \Gamma_{1}\left(t-s\right)^{1+\varepsilon_{1}}, \\ \|\delta A_{s,u,t}\|_{L^{m}} &\leq \Gamma_{2}\left(t-s\right)^{\frac{1}{2}+\varepsilon_{2}}. \end{split}$$

Then $\exists (\mathcal{A}_t)_{t \in [0,1]}$ s.t. $\forall t \in [0,1]$ and any sequence of partitions $\prod_k = \{t_i^k\}_{i=0}^{N_k}$ of [0, t] with mesh size going to zero,

$$\mathcal{A}_t = \lim_{k \to \infty} \sum_{i=0}^{N_k} \mathcal{A}_{t^k_i, t^k_{i+1}}$$
 in proba.

Moreover,
$$\exists C \ s.t. \ \forall (s,t) \in \Delta_{0,1}$$
,
 $\|\mathcal{A}_t - \mathcal{A}_s - \mathcal{A}_{s,t}\|_{L^m} \leq C \Gamma_1 (t-s)^{1+\varepsilon_1} + C \Gamma_2 (t-s)^{\frac{1}{2}+\varepsilon_2}$,
 $\|\mathbb{E}^s [\mathcal{A}_t - \mathcal{A}_s - \mathcal{A}_{s,t}]\|_{L^m} \leq C \Gamma_1 (t-s)^{1+\varepsilon_1}$.

Sewing approach Tamed Euler scheme Strong existence and uniqueness of the SDE

Elements of proof

It leads to key estimates for "smooth" f:

•
$$(\psi_t)$$
 is \mathbb{F} -adapted, $m \in [2, \infty)$, $p \in [m, \infty]$ and $\gamma < 0$ s.t.
 $(\gamma - d/p) > -1/(2H)$. Let $\alpha \in (0, 1)$ s.t. $H(\gamma - d/p - 1) + \alpha > 0$,

$$\left\| \int_s^t f(B_r + \psi_r) dr \right\|_{L^m(\Omega)} \leq C \|f\|_{\mathcal{B}_p^{\gamma}} (t - s)^{1 + H(\gamma - d/p)} + C \|f\|_{\mathcal{B}_p^{\gamma}} [\psi]_{\mathcal{C}_{[s,t]}^{\alpha}} L^m (t - s)^{1 + H(\gamma - d/p - 1) + \alpha}.$$
(1)

 \longrightarrow leads to existence via a tightness-stability argument.

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 $\left\| \int_s^t f(B_r + \psi_r) dr \right\|_{L^m(\Omega)} \le C \|f\|_{\mathcal{B}_p^{\gamma}} (t - s)^{1 + H(\gamma - d/p)} + C \|f\|_{\mathcal{B}_p^{\gamma}} [\psi]_{\mathcal{C}_{[s,t]}^{\alpha} L^m} (t - s)^{1 + H(\gamma - d/p - 1) + \alpha}.$
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 \longrightarrow leads to existence via a tightness-stability argument.

• $m \in [2, \infty)$ and $p \in [m, \infty]$ and $0 > \gamma > 1 - 1/(2H)$. For any \mathcal{F}_s -measurable $\kappa_1, \kappa_2 \in L^m(\Omega)$,

$$\left\|\int_{s}^{t}f(B_{r}+\kappa_{1})-f(B_{r}+\kappa_{2})dr\right\|_{L^{m}}$$

$$\leq C\|f\|_{\mathcal{B}_{p}^{\gamma}}\|\kappa_{1}-\kappa_{2}\|_{L^{m}}(t-s)^{1+H(\gamma-d/p-1)},$$
(2)

(for uniqueness).

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Elements of proof II

Why the condition $\gamma - \frac{d}{p} > \frac{1}{2} - \frac{1}{2H}$ in the theorem?

Consider (b^n) in $\mathcal{C}^{\infty} \cap \mathcal{B}_p^{\gamma}$ that approximates *b*. Let X^n be the solution with drift b^n .

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● We look for a priori estimate on the Hölder regularity of Xⁿ − B. If uniform in n, we get tightness.

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- **a** In (1), replace f by b^n , X by X^n and $K_t^n := \int_0^t b^n(X_s) ds \equiv \psi_t$. Then for any α such that $H(\gamma d/p 1) + \alpha > 0$,

$$\begin{split} \| \mathcal{K}_{t}^{n} - \mathcal{K}_{s}^{n} \|_{L^{m}(\Omega)} &\leq C \, \| b^{n} \|_{\mathcal{B}_{p}^{\gamma}}(t-s)^{1+\mathcal{H}(\gamma-d/p)} \\ &+ C \, \| b^{n} \|_{\mathcal{B}_{p}^{\gamma}} [\mathcal{K}^{n}]_{\mathcal{C}_{[s,t]}^{\alpha}L^{m}}(t-s)^{1+\mathcal{H}(\gamma-d/p-1)+\alpha}. \end{split}$$

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- We look for a priori estimate on the Hölder regularity of Xⁿ B. If uniform in n, we get tightness.
- **a** In (1), replace f by b^n , X by X^n and $K_t^n := \int_0^t b^n(X_s) ds \equiv \psi_t$. Then for any α such that $H(\gamma d/p 1) + \alpha > 0$,

$$\begin{split} \| \mathcal{K}_{t}^{n} - \mathcal{K}_{s}^{n} \|_{L^{m}(\Omega)} &\leq C \, \| b^{n} \|_{\mathcal{B}_{p}^{\gamma}}(t-s)^{1+\mathcal{H}(\gamma-d/p)} \\ &+ C \, \| b^{n} \|_{\mathcal{B}_{p}^{\gamma}} [\mathcal{K}^{n}]_{\mathcal{C}_{[s,t]}^{\alpha} L^{m}}(t-s)^{1+\mathcal{H}(\gamma-d/p-1)+\alpha} \end{split}$$

Obvious $\alpha = 1 + H(\gamma - d/p)$ above with $H(\gamma - d/p - 1) + \alpha > 0$ requires $\gamma - \frac{d}{p} > \frac{1}{2} - \frac{1}{2H}$. Then for t - s small enough,

$$[\mathcal{K}^n]_{\mathcal{C}^{\alpha}_{[s,t]}L^m} \leq C \|b^n\|_{\mathcal{B}^{\gamma}_p} + \frac{1}{2}[\mathcal{K}^n]_{\mathcal{C}^{\alpha}_{[s,t]}L^m}.$$

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Elements of proof II

Why the condition
$$\gamma - \frac{d}{p} > \frac{1}{2} - \frac{1}{2H}$$
 in the theorem?

Consider (b^n) in $\mathcal{C}^{\infty} \cap \mathcal{B}_p^{\gamma}$ that approximates *b*. Let X^n be the solution with drift b^n .

- We look for a priori estimate on the Hölder regularity of Xⁿ B. If uniform in n, we get tightness.
- **a** In (1), replace f by b^n , X by X^n and $K_t^n := \int_0^t b^n(X_s) ds \equiv \psi_t$. Then for any α such that $H(\gamma d/p 1) + \alpha > 0$,

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Obvious $\alpha = 1 + H(\gamma - d/p)$ above with $H(\gamma - d/p - 1) + \alpha > 0$ requires $\gamma - \frac{d}{p} > \frac{1}{2} - \frac{1}{2H}$. Then for t - s small enough,

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④ Extend to any $s \leq t$ and get tightness.

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Let h > 0 and (b^n) that approximates b in $\mathcal{B}_p^{\gamma^-}(\mathbb{R}^d)$. Consider the following tamed Euler scheme:

$$X_t^{h,n} = X_0 + \int_0^t b^n (X_{r_h}^{h,n}) dr + B_t,$$

where $r_h = h \lfloor \frac{r}{h} \rfloor$.

"Subcritical" case

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Theorem ([G.-Haress-Richard.'22])

Let
$$H < rac{1}{2}$$
, $m \ge 2$ and $p \in [m, \infty]$. Let $b \in \mathcal{B}_p^{\gamma}$ and assume $0 > \gamma - rac{d}{p} > 1 - rac{1}{2H}$.

Let X denote a weak solution such that $X - B \in C_{[0,T]}^{\frac{1}{2}+H}(L^m)$. Let $\varepsilon \in (0, \frac{1}{2})$. Then $\forall h \in (0, 1)$ and $\forall n \in \mathbb{N}$,

$$\begin{split} [X_t - X_t^{h,n}]_{\mathcal{C}^{\frac{1}{2}}L^m} &\leq C \Big(\|b^n - b\|_{\mathcal{B}^{\gamma-1}_{\rho}} + \|b^n\|_{\infty} h^{\frac{1}{2}-\varepsilon} \\ &+ \|b^n\|_{\infty} \|b^n\|_{\mathcal{C}^1} h^{1-\varepsilon} \Big). \end{split}$$

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Denote by G_t the Gaussian semigroup with variance t. Then

$$\begin{split} \|G_{\frac{1}{n}}b-b\|_{\mathcal{B}_{p}^{\gamma-1}} &\lesssim n^{-\frac{1}{2}} \|b\|_{\mathcal{B}_{p}^{\gamma}}, \\ \|G_{\frac{1}{n}}b\|_{\infty} &\lesssim n^{\frac{1}{2}(-\gamma+\frac{d}{p})} \|b\|_{\mathcal{B}_{p}^{\gamma}}, \\ \|G_{\frac{1}{n}}b\|_{\mathcal{C}^{1}} &\lesssim n^{\frac{1}{2}(1-\gamma+\frac{d}{p})} \|b\|_{\mathcal{B}_{p}^{\gamma}}. \end{split}$$

Corollary

Let
$$h \in (0, \frac{1}{2})$$
, $n_h = \lfloor h^{-\frac{1}{1-\gamma+\frac{d}{p}}} \rfloor$ and $b^{n_h} = G_{\frac{1}{n_h}}b$. Then

$$[X_t - X_t^{h,n_h}]_{C^{\frac{1}{2}}I^m} \leq C h^{\frac{1}{2(1-\gamma+\frac{d}{p})}-\varepsilon}.$$

"Critical" case

Theorem ([G.-Haress-Richard.'22])

Let
$$H < \frac{1}{2}$$
, $m \ge 2$ and $p \in [m, \infty]$. Let $b \in \mathcal{B}_p^{\gamma}$ and assume

$$\gamma - \frac{d}{p} = 1 - \frac{1}{2H} \text{ and } p < +\infty.$$

Let

$$\epsilon(h, n) = \|b - b^n\|_{\mathcal{B}^{\gamma-1}_p}(1 + |\log(\|b - b^n\|_{\mathcal{B}^{\gamma-1}_p})|) + \|b^n\|_{\infty}h^{\frac{1}{2}-\varepsilon} + \|b^n\|_{\mathcal{C}^1}\|b^n\|_{\infty}h^{1-\varepsilon}.$$

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Then $\exists C, \rho > 0$ such that for all $h \in (0, 1)$ and $n \in \mathbb{N}$,

$$[X_t - X_t^{h,n}]_{\mathcal{C}^{\frac{1}{2}-}L^m} \leq C\epsilon(h,n)^{\rho}.$$

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Rates

The orders of convergence obtained here compared to regular b from Butkovsky et al. (2021a); Dareiotis at al. (2021); De Angelis et Al. (2019) are:

Drift	Rate
$\alpha > 0$	$\left(rac{1}{2}+Hlpha ight)\wedge 1$
$\gamma - rac{d}{p} > 0$	$\left(rac{1}{2} + H\left(\gamma - rac{d}{p} ight) ight) \wedge 1 - arepsilon$
$\alpha = 0 \sim Bounded$	$\frac{1}{2}$
$\gamma - \frac{d}{p} = 0$	$\frac{1}{2} - \varepsilon$
$\gamma - rac{d}{ ho} \in \left(1 - rac{1}{2H}, 0 ight)$	$\frac{1}{2(1-\gamma+\frac{d}{p})}-\varepsilon$
$\gamma - rac{d}{p} = 1 - rac{1}{2H} ext{ and } p < \infty$	$\rho = He^{-M} - \varepsilon$

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Elements of proof I

Define

$$\mathcal{K}^n_t := \int_0^t b^n(X_r) dr ext{ and } \mathcal{K}^{h,n}_t := \int_0^t b^n(X^{h,n}_{r_h}) dr.$$

Decompose the error as follows:

$$X_{t} - X_{t}^{h,n} - (X_{s} - X_{s}^{h,n}) = K_{t} - K_{s} - (K_{t}^{n} - K_{s}^{n})$$
(3)

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$$+ \int_{s}^{t} (b^{n}(K_{r} + B_{r}) - b^{n}(K_{r}^{h,n} + B_{r}))dr$$
 (4)

$$+\int_{s}^{t}(b^{n}(K_{r}^{h,n}+B_{r})-b^{n}(K_{r_{h}}^{h,n}+B_{r_{h}}))dr.$$
 (5)

Denote by $E_{s,t}^{1,h,n}$ the term in (4), $E_{s,t}^{2,h,n}$ the term in (5), and $E_{s,t}^{h,n} = E_{s,t}^{1,h,n} + E_{s,t}^{2,h,n}$.

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Elements of proof II

The terms (3) and (4) are controlled "classically" by stochastic sewing:

$$[\mathcal{K}-\mathcal{K}^n]_{\mathcal{C}^{\frac{1}{2}}_{[s,t]}L^m} \leq C \|b-b^n\|_{\mathcal{B}^{\gamma-1}_p}$$

and

$$\|E_{s,t}^{\mathbf{1},h,n}\|_{L^m} \leq C([E^{h,n}]_{\mathcal{C}^{\frac{1}{2}}_{[s,t]}L^m} + \|b-b^n\|_{\mathcal{B}^{\gamma-1}_p})(t-s)^{1+H(\gamma-\frac{d}{p}-1)}.$$

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Elements of proof II

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and

$$\|E_{s,t}^{1,h,n}\|_{L^{m}} \leq C([E^{h,n}]_{\mathcal{C}^{\frac{1}{2}}_{[s,t]}L^{m}} + \|b-b^{n}\|_{\mathcal{B}^{\gamma-1}_{p}})(t-s)^{1+\mathcal{H}(\gamma-\frac{d}{p}-1)}.$$

The last term $E_{s,t}^{2,h,n}$ can be controlled using Girsanov, but this leads to an exponential dependence in $||b^n||_{\infty}$. Instead with use again the SSL to get

$$\begin{split} \| E_{s,t}^{2,h,n} \|_{L^m} &\leq C \Big((\| b^n \|_{\infty} + 1) \, h^{\frac{1}{2}} \, (t-s)^{1+H(\gamma - \frac{d}{p} - 1)} \\ &+ \| b^n \|_{\infty} \, h^{\frac{1}{2} - \varepsilon} \, |t-s|^{\frac{1}{2} + \varepsilon} \\ &+ \| b^n \|_{\mathcal{C}^1} \, \| b^n \|_{\infty} \, h^{1-\varepsilon} \, (t-s)^{1+\varepsilon} \Big). \end{split}$$

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Consequences

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Definition

- Pathwise uniqueness holds if for any solutions (X, B) and (Y, B) defined on the same filtered probability space with the same B and same initial condition X_0 , X and Y are indistinguishable.
- A weak solution (X, B) such that X is \mathbb{F}^{B} -adapted is called a *strong* solution.

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Strong existence and uniqueness

As a consequence of the convergence of the Euler scheme,

Theorem ([G.-Haress-Richard.'22])

Let
$$H < \frac{1}{2}$$
, $\gamma \in \mathbb{R}$, $p \in [1, \infty]$ and $b \in \mathcal{B}_p^{\gamma}$. Assume that

$$0>\gamma-rac{d}{p}\geq 1-rac{1}{2H}$$
 and $\gamma>1-rac{1}{2H}$

- There exists a strong solution X to (*) such that $[X B]_{C^{1/2+H}_{[0,1]}L^{m,\infty}} < \infty$ for any $m \ge 2$.
- Pathwise uniqueness holds in the class of solutions such that $[X B]_{C_{[0,1]}^{1/2+H}L^{2,\infty}} < \infty.$

Sewing approach Tamed Euler scheme Strong existence and uniqueness of the SDE

Strong existence and uniqueness

As a consequence of the convergence of the Euler scheme,

Theorem ([G.-Haress-Richard.'22])

Let
$$H < \frac{1}{2}$$
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$$0>\gamma-rac{d}{p}\geq 1-rac{1}{2H}$$
 and $\gamma>1-rac{1}{2H}$

- There exists a strong solution X to (*) such that $[X B]_{C_{[0,1]}^{1/2+H}L^{m,\infty}} < \infty$ for any $m \ge 2$.
- Pathwise uniqueness holds in the class of solutions such that $[X B]_{C_{[0,1]}^{1/2+H}L^{2,\infty}} < \infty.$
- If $\gamma \frac{d}{p} > 1 \frac{1}{2H}$, for all $\eta \in (0, 1)$, pathwise uniqueness holds in the class of solutions such that $[X B]_{C_{[0,1]}^{H(1-\gamma+d/p)+\eta}L^{2,\infty}} < \infty$.

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Finite differences Controlling the error

Stochastic PDEs

Consider

$$\partial_t u(t,x) = \frac{1}{2} \partial_{xx}^2 u(t,x) + \frac{b}{b}(u(t,x)) + \xi \qquad (\star)$$

where ξ is a space-time white noise and **b** is a distribution in some Besov space, with bounded mesurable initial data ψ_0 .

In [Athreya et al.'20], it is proven that there exists a weak solution with certain regularity. The goal is to approximate it.

Finite differences Controlling the error

Stochastic PDEs

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where ξ is a space-time white noise and **b** is a distribution in some Besov space, with bounded mesurable initial data ψ_0 .

In [Athreya et al.'20], it is proven that there exists a weak solution with certain regularity. The goal is to approximate it.

Consider a sequence b^k of smooth function which approximates the distribution b in some sense.

We say that a sequence of smooth bounded functions (b^k) converges to $\frac{b}{p}$ in $\mathcal{B}_p^{\gamma-}$ as k goes to infinity if

$$\left\{ egin{array}{l} \sup_{k\in\mathbb{N}} \|b^k\|_{\mathcal{B}^\gamma_p} < \|b\|_{\mathcal{B}^\gamma_p} < \infty \ \lim_{k o\infty} \|b^k - b\|_{\mathcal{B}^{\gamma'}_p} = 0 \qquad orall \gamma' < \gamma. \end{array}
ight.$$

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Definition of solution

Definition

- A couple $((u_t(x))_{\substack{t\in[0,1]\\x\in[0,1]}},\xi)$ is a weak solution on some filtered space $(\Omega,\mathbb{P},\mathbb{F})$ if there exists a process $K:[0,1]\times[0,1]\times\Omega\to\mathbb{R}$ such that
- (1) ξ is an \mathbb{F} -space time white noise.
- (2) u is adapted to \mathbb{F} .
- (3) $u_t(x) = P_t \psi_0(x) + K_t(x) + O_t(x)$ a.s where $x \in [0, 1], t \in [0, 1]$.
- (4) For any sequence $(b^k)_{k\in\mathbb{N}}$ in \mathcal{C}^b_∞ converging to b in $\mathcal{B}^{\gamma-}_p$, we have

$$\sup_{\substack{t\in[0,1]\\x\in[0,1]}}\left|\int_0^t\int_0^1p_{t-r}(x,y)b^k(u_r(y))\mathrm{d}y\mathrm{d}r-K_t(x)\right|\underset{k\to\infty}{\xrightarrow{\mathbb{P}}}0.$$

(5) Almost surely, the function u is continuous on $[0,1] \times [0,1]$. If the couple is clear from the context, we simply say that u is a weak solution.

Finite differences Controlling the error

Mild form and Gaussian operators

The *mild* form associated to the SPDE is

$$u_t(x) = P_t \psi_0(x) + \int_0^t \int_0^1 p_{t-r}(x, y) b(u_r(y)) dy dr + O_t(x)$$
.

Notice that the *mild* form is also not well-posed when b is a genuine distribution. To define a solution, we first specify in which spaces we take b, and then define how we approximate b via a smooth sequence.

Finite differences Controlling the error

Mild form and Gaussian operators

We encounter different heat kernels: the continuum Gaussian on $\mathbb R,$

 $g_t(x) = \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{x^2}{2t}\right)$, the continuum heat kernel on [0, 1] associated with the boundary conditions

$$p_t(x,y) = p_t(x-y) = \sum_{k \in \mathbb{Z}} \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{(x-y+k)^2}{4t}\right) = \sum_{k \in \mathbb{Z}} e^{-4\pi^2 k^2 t} e^{i2\pi k(x-y)}.$$

We denote by *G*. and *P*. the respective convolutions with the *g*. and *p*.. That is, for any bounded measurable function f, we write

$$G_t f(x) = \int_0^1 g_t(x-y)f(y)dy$$
, and $P_t f(x) = \int_0^1 p_t(x-y)dy$.

We also denote the convolution operator by $(f \star g)(x) = \int f(x-y)g(y)dy$.
Finite differences Controlling the error

Mild form and Gaussian operators

We denote by
$$Q(t)$$
 the variance of the Ornstein-Uhlenbeck process
 $O_t(x) = \int_0^t \int_0^1 p_{t-r}(x, y)\xi(\mathrm{d}y, \mathrm{d}r)$. In fact, for all $x \in [0, 1]$

$$\mathbb{E}\left(O_t(x)^2\right) = \int_0^t \int_0^1 p_t(x-y)^2 \mathrm{d}y \mathrm{d}r = \int_0^t \int_0^1 p_{2t}(y) \mathrm{d}y \mathrm{d}r =: Q(t).$$

Moreover, writing $Z_{s,t}(x) = O_t(x) - P_{t-s}O_s(x)$ for $t \ge s$, we have that the random variable $Z_{s,t}(x)$ is independent of \mathcal{F}_s and

$$\mathbb{E}\Big(Z_{s,t}(x)\Big)^2 = Q(t-s).$$

The following equality will be used a lot. For any continuous function h and \mathcal{F}_s -measurable random variable Y one has the almost sure equality

$$\mathbb{E}^{s}h(O_{t}(x)+Y)=G_{Q(t-s)}h(P_{t-s}O_{s}(x)+Y).$$

Finite differences Controlling the error

Finite differences

We study a tamed Euler finite-difference.



Finite differences Controlling the error

Finite differences

We study a tamed Euler finite-difference.

Fix $k \in \mathbb{N}$, such that b^k is close to b.



Finite differences Controlling the error

Finite differences

We study a tamed Euler finite-difference.

Fix $k \in \mathbb{N}$, such that b^k is close to b.

Let $h \in (0,1)$ be a time step of the form $h = c(2n)^{-2}$ for some $n \in \mathbb{N}$, where c is a constant satisfying the CFL condition $c > \frac{1}{2}$.

Finite differences Controlling the error

Finite differences

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Fix $k \in \mathbb{N}$, such that b^k is close to b.

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We introduce the following space and time grids.

$$\Pi_n = \left\{0, (2n)^{-1}, \ldots, (2n-1)(2n)^{-1}\right\}, \quad \Lambda_h = \left\{0, h, 2h, \ldots\right\}.$$

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Finite differences

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We introduce the following space and time grids.

$$\Pi_n = \left\{0, (2n)^{-1}, \ldots, (2n-1)(2n)^{-1}\right\}, \quad \Lambda_h = \left\{0, h, 2h, \ldots\right\}.$$

We can now define the numerical scheme for $x \in \Pi_n$ and $t \in \Lambda_h$ as

$$\begin{cases} u_{t+h}^{h,k}(x) = u_t^{h,k}(x) + h\Delta_n u_t^{h,k}(x) + hb^k \left(u_t^{h,k}(x) \right) + h\eta_{h,n}(t,x) \\ u_0^{h,k}(x) = \psi_0(x), \end{cases}$$

Finite differences Controlling the error

Finite differences

 Δ_n is the discrete Laplacian

$$\Delta_n f(x) = (2n)^2 \left(f\left(x + (2n)^{-1}\right) - 2f(x) + f\left(x - (2n)^{-1}\right) \right),$$

and discrete noise $\eta_{h,n}$ is given by

$$\eta_h(t,x) = (2n)h^{-1}\xi([t,t+h] \times [x,x+(2n)^{-1}]).$$

Finite differences Controlling the error

The goal is the rate of convergence

Rate of convergence

For the right choice of b^k and k, we prove the following rate of convergence for the approximation $u^{h,k}$

$$\sup_{\substack{t\in\Lambda_h\\\epsilon\in\Pi_n}}||u_t-u_t^{h,k}||_{L^m(\Omega)}\leq C\left(n^{-\frac{1}{2(1-\gamma+\frac{1}{p})}}\right).$$

Finite differences Controlling the error

Approximated operator

Consider the functions $e_j(x) = e^{i2\pi jx}$ for $j \in \mathbb{Z}$. They are eigenfunctions of Δ with eigenvalues $\lambda_j = -4\pi^2 j^2$. It is well known that $(e_j)_{j\in\mathbb{Z}}$ forms an orthonormal basis of $L^2([0,1],\mathbb{C})$.

The eigenvalues of the discrete Laplacian Δ_h are

$$\lambda_j^n = -16n^2 \sin^2\left(rac{j\pi}{2n}
ight) \; ext{for j} \; \in \mathbb{Z} \; .$$

Finite differences Controlling the error

Approximated operator

We know that for $-n \leq j, l \leq n-1$,

$$\Delta_h e_j(x) = \lambda_j^h e_j(x),$$

and

$$\frac{1}{2n}\sum_{x\in\Pi_n}e_j(x)\overline{e_\ell(x)}=1_{j=\ell}.$$

As a consequence, e_i for $i \in [-n, n-1]$, as functions on Π_n form a basis of $L^2(\Pi_n; \mathbb{C})$.

It will be convenient to use the piecewise linear extension of the restriction of e_j to Π_n : for $-n \le j \le n-1$, for $x \in \Pi_n$, and $x' \in [x, x + (2n)^{-1}]$, set

$$e_{j}(x') = e_{j}(x) + (2n)(x'-x)(e_{j}(x+(2n)^{-1})-e_{j}(x)).$$

Finite differences Controlling the error

Approximated operator

It remains to encode the temporal discretisation.

Naturally, on the temporal gridpoints t = kh a factor $(1 + h\lambda_j^n)^k$ appears.

Between the gridpoints, we again interpolate linearly. More precisely, for $j = -n, \ldots, n-1$, for $t \in \Lambda_h$, and $t' \in [t, t+h]$, set

$$\mu_{j}^{h}\left(t'\right)=\left(1+h\lambda_{j}^{n}\right)^{th^{-1}}+h^{-1}\left(t'-t\right)\left(\left(1+h\lambda_{j}^{n}\right)^{(t+h)h^{-1}}-\left(1+h\lambda_{j}^{n}\right)^{th^{-1}}\right).$$

Discrete mild form

We can now define the discrete heat kernel and discrete convolution. Our goal is to write the numerical scheme in a *mild* form similar to classical mild form for SPDEs.

For $t \in [0, 1]$ and $x \in [0, 1]$, denote by t_h and x_n the leftmost gridpoint from t in Λ_h and from x in Π_n respectively.

The *mild* form associated to the scheme is

$$u_t^{h,k}(x) = P_t^n \psi_0(x) + \int_0^t P_{(t-s)_h}^n b^k \left(u_{s_h}^{h,k} \right)(x) \mathrm{d}s + \int_0^t \int_0^1 p_{(t-s)_h}^n(x,y) \xi(\mathrm{d}y,\mathrm{d}s)$$

where P^n and p^n are respectively the discrete analogues of P and p.

Finite differences Controlling the error

Discrete mild form

They are defined for all $t \in [0,1]$ and $x \in [0,1]$

$$P_t^n f(x) := p_t^n \star_n f \text{ and } p_t^n(x,y) = \sum_{j=-n}^{n-1} \mu_j^n(t) e_j^n(x) \overline{e_j^n(y_n)}.$$

Moreover, \star_n denotes the discrete convolution

$$g \star_n f(x) := \int_0^1 g(x-y)f(y_n)\mathrm{d}y.$$

Finite differences Controlling the error

Ornstein-Uhlenbeck process

Definition

We define the discrete Ornstein-Uhlenbeck process as

$$\mathcal{O}_t^n(x) := \int_0^t \int_0^1 p^h_{(t-r)_h}(x,y) \xi(\mathrm{d} y,\mathrm{d} r) \ ,$$

Analogously to O_t , for $s \leq t$, we define $\widehat{O}^h_{s,t}$ and $Z^h_{s,t}$ by

$$\begin{aligned} \mathcal{O}_t^n(x) &= \int_0^s \int_0^1 p_{(t-r)_h}^n(x,y) \xi(dy,dr) + \int_s^t \int_0^1 p_{(t-r)_h}^n(x,y) \xi(\mathrm{d}y,\mathrm{d}r) \\ &=: \widehat{\mathcal{O}}_{s,t}^n + Z_{s,t}^n. \end{aligned}$$

Finite differences Controlling the error

Ornstein-Uhlenbeck process

Notice that $Z_{s,t}^n(x)$ is a random variable independent of \mathcal{F}_s and has variance

$$\begin{split} \mathbb{E}\Big(Z_{s,t}^{n}(x)^{2}\Big) &= \int_{0}^{t-s} \int_{0}^{1} \left|p_{r_{n}}^{n}(x,y)\right|^{2} \mathrm{d}y \mathrm{d}r \\ &= \int_{0}^{t-s} \sum_{j=-n}^{n-1} \left|1 + h\lambda_{j}^{n}\right|^{2r_{h}h^{-1}} \mathrm{d}r =: Q^{n}(t-s) \;. \end{split}$$

Also similarly to O_t , we have that for any continuous function h and \mathcal{F}_s -measurable random variable Y

$$\mathbb{E}^{s}h(O_{t}^{n}(x)+Y)=G_{Q^{n}(t-s)}h\left(\widehat{O}_{s,t}^{n}(x)+Y\right) \ .$$

Singular model of equatio

- Numerical simulations
- SDE Weak solutions

2 Sewing approach and Tamed Euler scheme

- Sewing approach
- Tamed Euler scheme
- Strong existence and uniqueness of the SDE

Tamed Euler scheme for SPDE Finite differences

Controlling the error

Controlling the error

Finite differences Controlling the error

We are interested in controlling the error $\mathcal{E}^{h,k}$ between the solution u and the numerical scheme $u^{h,k}$, defined for $(s,t) \in \Delta_{0,1}$ and $x \in [0,1]$ by

$$\mathcal{E}_{s,t}^{h,k}(x) = u_t(x) - P_{t-s}u_s(x) - \int_s^t P_{(t-s)_h}^n b^k(u_{r_h}^{h,k})(x) dr.$$

Finite differences Controlling the error

Elements of Proof I

For all $(s,t) \in \Delta_{0,1}$ and $x \in [0,1]$, we write

$$\begin{split} \mathcal{E}_{s,t}^{h,k}(x) &= v_t(x) - P_{t-s}v_s - \int_s^t P_{(t-r)_h}^n b^k (v_{r_h}^{h,k} + P_{r_h}^n \psi_0 + O_{r_h}^n)(x) \mathrm{d}s \\ &= v_t(x) - v_t^k(x) - P_{t-s}v_s(x) + P_{t-s}v_s^k(x) \\ &+ \int_s^t \left(P_{(t-r)} b^k (v_r + P_r \psi_0 + O_r)(x) \\ &- \int_s^t P_{(t-r)_h}^n b^k (v_{r_h}^{h,k} + P_{r_h}^n \psi_0 + O_{r_h}^n(x))(x) \right) \mathrm{d}s \\ &:= V_t^k - P_{t-s}V_s^k + \mathcal{E}_{s,t}^{1,h,k} + \mathcal{E}_{s,t}^{2,h,k} + \mathcal{E}_{s,t}^{3,h,k}, \\ &:= \epsilon(h,k) + \mathcal{E}_{s,t}^{1,h,k} \end{split}$$

Finite differences Controlling the error

Elements of Proof II

$$\begin{split} \mathcal{E}_{s,t}^{1,h,k} &= \int_0^t \int_0^1 p_{t-r}(x,y) \Big(b^k (v_r(y) + P_r \psi_0(y) + O_r(y)) \\ &\quad - b^k (v_r^{h,k}(y) + P_r^n \psi_0(y) + O_r^n(y)) \Big) \mathrm{d}y \mathrm{d}r \\ \mathcal{E}_{s,t}^{2,h,k} &= \int_0^t \int_0^1 p_{t-r}(x,y) \Big(b^k (v_r^{h,k}(y) + P_r^n \psi_0(y) + O_r^n(y)) \\ &\quad - b^k (v_{r_h}^{h,k}(y_n) + P_{r_h}^n \psi_0(y_n) + O_{r_h}^n(y_n)) \Big) \mathrm{d}y \mathrm{d}r \\ \mathcal{E}_{s,t}^{3,h,k} &= \int_0^t \int_0^1 (p_{t-r} - p_{(t-r)_h}^n)(x,y) b^k (v_{r_h}^{h,k}(y_n) + P_{r_h}^n \psi_0(y_n) + O_{r_h}^n(y_n)) \mathrm{d}y \mathrm{d}r. \end{split}$$

will be controlled on small intervals.

Finite differences Controlling the error

Elements of Proof III

On all intervals [S, T], we have

$$[V^k]_{\mathcal{C}_{[S,T]}^{\frac{1}{2}}L^m} \leq C \|b-b^k\|_{\mathcal{B}_p^{\gamma-1}}.$$

$$\begin{split} [\mathcal{E}^{2,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,T]}L^{m}} + [\mathcal{E}^{3,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,T]}L^{m}} \\ & \leq C\Big((1+\|b^{k}\|_{\infty})n^{-\frac{1}{2}+\varepsilon} + (1+\|b^{k}\|_{\infty})(1+\|b^{k}\|_{\mathcal{C}^{1}})n^{-1+\varepsilon}\Big). \end{split}$$

Finite differences Controlling the error

Elements of Proof III

On all intervals [S, T], we have

$$[V^k]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^m} \leq C \|b-b^k\|_{\mathcal{B}^{\gamma-1}_p}.$$

$$\begin{split} [\mathcal{E}^{2,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,7]}L^{m}} + [\mathcal{E}^{3,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,7]}L^{m}} \\ & \leq C\Big((1+\|b^{k}\|_{\infty})n^{-\frac{1}{2}+\varepsilon} + (1+\|b^{k}\|_{\infty})(1+\|b^{k}\|_{\mathcal{C}^{1}})n^{-1+\varepsilon}\Big). \end{split}$$

which reads

$$\epsilon(h,k) \leq C \Big(\|b-b^k\|_{\mathcal{B}^{\gamma-1}_{\rho}} + (1+\|b^k\|_{\infty})n^{-\frac{1}{2}+\varepsilon} + (1+\|b^k\|_{\infty})(1+\|b^k\|_{\mathcal{C}^1})n^{-1+\varepsilon} \Big).$$

Finite differences Controlling the error

Elements of Proof III

On all intervals [S, T], we have

$$[V^k]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^m} \leq C \|b-b^k\|_{\mathcal{B}^{\gamma-1}_p}.$$

$$\begin{split} [\mathcal{E}^{2,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,\tau]} \mathcal{L}^{m}} + [\mathcal{E}^{3,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[5,\tau]} \mathcal{L}^{m}} \\ & \leq C \Big((1 + \|b^{k}\|_{\infty}) n^{-\frac{1}{2} + \varepsilon} + (1 + \|b^{k}\|_{\infty}) (1 + \|b^{k}\|_{\mathcal{C}^{1}}) n^{-1 + \varepsilon} \Big). \end{split}$$

which reads

$$\epsilon(h,k) \leq C \Big(\|b-b^k\|_{\mathcal{B}^{\gamma-1}_p} + (1+\|b^k\|_{\infty}) n^{-\frac{1}{2}+\varepsilon} + (1+\|b^k\|_{\infty}) (1+\|b^k\|_{\mathcal{C}^1}) n^{-1+\varepsilon} \Big).$$

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The last step is to obtain

$$[\mathcal{E}^{1,h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^{m}} \leq C\Big([\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^{m}} + [\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[0,S]}L^{m}} + \epsilon(h,k)\Big)(T-S)^{\frac{1}{4}(\gamma+1-1/p)}.$$

Finite differences Controlling the error

Elements of Proof IV

Hence the bound

$$[\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^{m}} \leq \epsilon(h,k) + C\Big([\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[S,T]}L^{m}} + [\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[0,S]}L^{m}}\Big)(T-S)^{\frac{1}{4}(\gamma+1-1/p)}$$

leads to

$$\left[\mathcal{E}^{h,k}\right]_{\mathcal{C}^{\frac{1}{2}}_{[0,1]}L^m} \leq C\epsilon(h,k),$$

which is controlled.

Finite differences Controlling the error

Theoretical Results

Let $\gamma \in \mathbb{R}$, $\textbf{\textit{p}} \in [1,\infty]$ such that

$$0 > \gamma - \frac{1}{p} \ge -1$$
 and $\gamma > -1$. (A1)

Let
$$\mathbf{b} \in \mathcal{B}_{p}^{\gamma}$$
, $m \in [2, \infty)$, $\varepsilon \in (0, 1/2)$ and let $\psi_{0} \in \mathcal{C}^{\frac{1}{2}-\varepsilon}([0, 1], \mathbb{R})$.

Let u be the strong solution to the SPDE with drift b.

Let (b^k) be a sequence of smooth functions that converges to \underline{b} in $\mathcal{B}_p^{\gamma-}$ and $(u^{h,k})_{h\in(0,1),k\in\mathbb{N}}$ be the tamed Euler finite-differences scheme defined on the same probability space and with the same space-time white noise ξ as u.

Finite differences Controlling the error

Theoretical Results

Theorem (G.-Haress-Richard)

(a) <u>Regularity of the tamed Euler scheme</u>: Let $\eta \in \left(0, \frac{1}{2}\right)$, \mathcal{D} be a subset of $[0, 1] \times \mathbb{N}$ and assume that

$$\sup_{(h,k)\in\mathcal{D}} \|b^k\|_{\infty} h^{\frac{1}{4}-\eta} < \infty \quad \text{and} \quad \sup_{(h,k)\in\mathcal{D}} \|b^k\|_{\mathcal{C}^1} h^{\frac{1}{2}} < \infty, \tag{A2}$$

then
$$\sup_{(h,k)\in\mathcal{D}} \{u^{h,k} - O\}_{\mathcal{C}^{\frac{1}{2}+\eta}_{[\mathbf{0},\mathbf{1}]}L^{m,\infty}} < \infty.$$

Finite differences Controlling the error

Theoretical Results

Theorem (G.-Haress-Richard)

Assume that
$$[u - O]_{\mathcal{C}^{\mathbf{3/4}}_{[\mathbf{0},\mathbf{1}]}L^{m,\infty}} < \infty.$$

(b) <u>The sub-critical case</u>: If $-1 < \gamma - d/p < 0$, then there exists a constant C that depends on $m, p, \gamma, \varepsilon, \|b\|_{\mathcal{B}_p^{\gamma}}, \|\psi_0\|_{C^{\frac{1}{2}-\varepsilon}}$ such that for all $h \in (0, 1)$ and $k \in \mathbb{N}$, the following bound holds:

$$[\mathcal{E}^{h,k}]_{\mathcal{C}^{\frac{1}{2}}_{[0,1]}L^{m}} \leq C\left(\|b^{k}-b\|_{\mathcal{B}^{\gamma-1}_{p}} + (1+\|b^{k}\|_{\infty})n^{-\frac{1}{2}+\varepsilon} + \|b^{k}\|_{\infty}\|b^{k}\|_{\mathcal{C}^{1}}n^{-1+\varepsilon}\right).$$

Finite differences Controlling the error

Theoretical Results

Theorem (G.-Haress-Richard)

Assume that
$$[u - O]_{\mathcal{C}^{\mathbf{3/4}}_{[\mathbf{0},\mathbf{1}]}L^{m,\infty}} < \infty.$$

(c) <u>The critical case</u>: If $\gamma - 1/p = -1$ and $p < +\infty$. If (A2) holds, then there exists two constants C_1, C_2 that depend on $m, p, \gamma, \varepsilon, \|b\|_{\mathcal{B}_p^{\gamma}}, \|\psi_0\|_{\mathcal{C}^{\frac{1}{2}-\varepsilon}}$ such that for all $h \in (0,1)$ and $k \in \mathbb{N}$, the following bound holds:

$$egin{aligned} & [\mathcal{E}_{0,\cdot}^{h,k}]_{L^{\infty}_{[0,1]}L^{m}} \leq C_{1} \Big(\|b-b^{k}\|_{\mathcal{B}^{\gamma-1}_{p}} (1+|\log\|b-b^{k}\|_{\mathcal{B}^{\gamma-1}_{p}}) + (1+\|b^{k}\|_{\infty}) n^{-rac{1}{2}+arepsilon} \ & + (1+\|b^{k}\|_{\infty}) (1+\|b^{k}\|_{\mathcal{C}^{1}}) n^{-1+arepsilon} \Big)^{C_{2}}. \end{aligned}$$

Finite differences Controlling the error

Theoretical Results

Regularity	$\gamma - \frac{1}{p} = 0$	$\gamma-\frac{1}{p}\in(-1,0)$	$\gamma-rac{1}{p}=-1$ and $p<\infty$
Space Order	$rac{1}{2}-arepsilon$	$\frac{1}{2-2(\gamma-\frac{1}{p})}-\varepsilon$	<i>C</i> > 0
Time Order	$rac{1}{4} - arepsilon$	$\frac{1}{4-4(\gamma-\frac{1}{p})}-\varepsilon$	C/2 > 0

Table: Rate of convergence of the tamed Euler finite-differences scheme depending on the Besov regularity of the drift.

Finite differences Controlling the error

Numerical simulation - Stochastic heat equation with Dirac drift



Figure: Approximate slope is 0.36

Finite differences Controlling the error

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Numerical simulation - regularized Dirac in 0



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Numerical simulation - Dirac in 0



Ludovic Goudenège - CNRS New way of proof

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Numerical simulation - Dirac in 1



Thanks for your attention !

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