

## Modelling and analysis of surface damage problems

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**joint research with**

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## Contact problems with adhesion

Applications to

- ▶ machine designing and manufacturing (use of **adhesive materials** in automotive and aerospace industry...)
- ▶ use of **layered composite structures** in building and civil engineering
- the interface regions between laminates affect the strength and stability of the structural elements
- the degradation of the adhesive substance on such regions may lead to material failure



**surface damage models**

[Frémond, '80s-'90s & "Non-smooth thermomechanics" 2002]

⇒ **energy and dissipation concentrated** on the contact surface

## The model

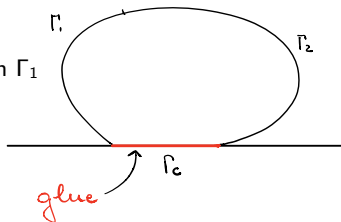
We consider  
a thermoviscoelastic body  $\Omega \subset \mathbb{R}^3$  which is in

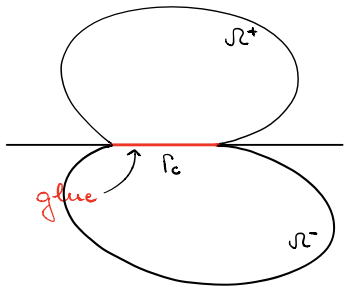
**contact with adhesion**

with a rigid support on a **(flat)** prescribed part  $\Gamma_c$  of its boundary

$$\partial\Omega = \Gamma_1 \cup \Gamma_2 \cup \Gamma_c$$

- assigned displacement on  $\Gamma_1$
- assigned traction on  $\Gamma_2$







## Related literature

(on static, quasistatic, dynamic **contact problems** with or without friction, with or without adhesion/delamination, mainly in the **isothermal case**):

- ▶ .....
- ▶ Ballard, Cocou, Jean, Lebon, Léger, Point, Pratt, Raous
- ▶ Andersson, Andrews, Klarbring, Kuttler, Shillor, Wright, Sofonea, Telega
- ▶ Martins, Monteiro Marques, Oden
- ▶ Migórski, Mantic, Kruzič, Panagiotopoulos
- ▶ Bock, Eck, Jarušek, Krbec, Schatzman
- ▶ Kočvara, Mielke, Roubiček, Thomas
- ▶ .....

## The model: the variables

♣ In the **isothermal case**

▶ in the **bulk domain**  $\Omega$ :

$\varepsilon(\mathbf{u})$  symm. linearized strain tensor

( $\mathbf{u}$  small displacement)

▶ on the **contact surface**  $\Gamma_c$ :

$\chi$  (scalar) **adhesion** parameter

“phase parameter”  $\sim$  proportion of active bonds between body & support

## The equations for $\mathbf{u}$ and $\chi$

- ♣ Equations for  $\mathbf{u}$  and  $\chi$  are recovered from the **principle of virtual powers**
- ♣ The **energy balance** of the system also includes **micro-forces and micro-motions**, according to M. Frémond's approach

► **momentum balance:**

$$\left\{ \begin{array}{l} -\operatorname{div} \sigma = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\ \left\{ \begin{array}{l} \sigma \mathbf{n} = \mathbf{R} \quad \text{in } \Gamma_c \times (0, T), \\ \mathbf{u} = \mathbf{0} \quad \text{in } \Gamma_1 \times (0, T), \\ \sigma \mathbf{n} = \mathbf{g} \quad \text{in } \Gamma_2 \times (0, T), \end{array} \right. \end{array} \right.$$

$$\left\{ \begin{array}{l} \sigma \text{ stress tensor} \\ \mathbf{R} \text{ reaction on the contact surface} \\ \mathbf{f} \text{ volume force, } \mathbf{g} \text{ traction} \end{array} \right.$$



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► **balance equation for microscopic motions:**

$$\left\{ \begin{array}{l} B - \operatorname{div}_s \mathbf{H} = a \quad \text{in } \Gamma_c \times (0, T), \\ \mathbf{H} \cdot \mathbf{n}_s = 0 \quad \text{on } \partial\Gamma_c \times (0, T), \end{array} \right. \quad \left\{ \begin{array}{l} B, \mathbf{H} \text{ microscopic internal forces} \\ a \text{ microscopic external source} \end{array} \right.$$

## Energy and dissipation functionals

Constitutive laws for  $\sigma$ ,  $\mathbf{R}$ ,  $B$ ,  $\mathbf{H}$  are given in terms of **volume & surface free energies**

$$\Psi_{\Omega} = \Psi_{\Omega}(\varepsilon(\mathbf{u})), \quad \Psi_{\Gamma_c} = \Psi_{\Gamma_c}(\mathbf{u}|_{\Gamma_c}, \chi, \nabla\chi)$$

and the **volume & surface potentials of dissipation**

$$\Phi_{\Omega} = \Phi_{\Omega}(\varepsilon(\dot{\mathbf{u}})), \quad \Phi_{\Gamma_c} = \Phi_{\Gamma_c}(\dot{\chi}, \dot{\mathbf{u}}|_{\Gamma_c})$$

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↪ **non-smooth (multivalued) operators** in the equations
- [Raous, Cangémi, Cocou, '99] for a model close to the present one;
- [Del Piero, Raous, '10] for general models coupling friction, adhesion and unilateral contact.

## The adhesion phenomenon

**Notation** for the normal and tangential components of displacement vector  $\mathbf{u}$  and stress vector  $\sigma \mathbf{n}$

$$\mathbf{u} = u_N \mathbf{n} + \mathbf{u}_T, \quad u_N = u_i n_i, \quad \sigma \mathbf{n} = \sigma_N \mathbf{n} + \sigma_T, \quad \sigma_N = \sigma_{ij} n_i n_j$$

with  $\mathbf{n} = (n_i)$  outward normal unit vector to  $\partial\Omega$ .

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- The “surface damage parameter”  $\chi \sim$  **fraction of active glue fibers** at each point of the contact surface
  - ▶  $\chi = 0$  no adhesion (completely broken bonds)
  - ▶  $\chi = 1$  complete adhesion (unbroken bonds)
  - ▶  $0 < \chi < 1$  partial adhesion

We have to enforce

$$\chi \in [0, 1]$$

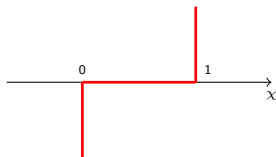
## The adhesion phenomenon

We impose the constraint  $\chi \in [0, 1]$  by the term  $l_{[0,1]}(\chi)$  in the surface energy functional

$$\Psi_{\Gamma_c} = \frac{1}{2}\chi|\mathbf{u}|^2 + l_{(-\infty,0]}(\mathbf{u}_N) + \omega(1-\chi) + \frac{1}{2}|\nabla_s \chi|^2 + l_{[0,1]}(\chi)$$

$\Rightarrow$   $l_{[0,1]}(\chi)$  in eq. for  $\chi$

$$\partial l_{[0,1]}(\chi) = \begin{cases} (-\infty, 0], & \text{if } \chi = 0, \\ 0, & \text{if } 0 < \chi < 1, \\ [0, +\infty), & \text{if } \chi = 1. \end{cases}$$



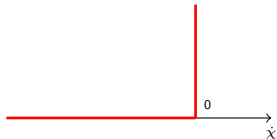
## The adhesion phenomenon

- If the “damage” of the glue is **irreversible**, we enforce  $\dot{\chi} \leq 0$  by the term  $l_{(-\infty, 0]}(\dot{\chi})$  in the surface dissipation potential

$$\Phi_{\Gamma_c} = \frac{1}{2}|\dot{\chi}|^2 + l_{(-\infty, 0]}(\dot{\chi})$$

⇒  $\partial l_{(-\infty, 0]}(\dot{\chi})$  in eq. for  $\chi$

$$\partial l_{(-\infty, 0]}(\dot{\chi}) = \begin{cases} 0, & \text{if } \dot{\chi} < 0, \\ [0, +\infty), & \text{if } \dot{\chi} = 0. \end{cases}$$





## The PDE system: the evolution of the adhesion

The evolution of the adhesion on the contact surface is ruled by

$$\begin{aligned} \dot{\chi} - \Delta_s \chi + \partial I_{[0,1]}(\chi) + \partial J_{-\infty,0]}(\dot{\chi}) &\ni \omega - \frac{1}{2}|\mathbf{u}|^2 && \text{on } \Gamma_c \times (0, T) \\ \partial_{\mathbf{n}_s} \chi &= 0, && \text{on } \partial\Gamma_c \times (0, T) \end{aligned}$$

- ▶  $\partial I_{[0,1]}(\chi) \Rightarrow \chi \in [0, 1]$  **(physical consistency)**
- ▶  $\partial J_{-\infty,0]}(\dot{\chi}) \Rightarrow \dot{\chi} \leq 0$  **(irreversible adhesion)**
- ▶  $\omega > 0$  constant (coefficient of internal cohesion)
- ▶  $-\frac{1}{2}|\mathbf{u}|^2$  source of damage due to displacement.

## The unilateral contact

- The **normal reaction** on  $\Gamma_c$  has to ensure the **impenetrability condition**

$$u_N \leq 0 \quad \text{on } \Gamma_c$$

and to render the **Signorini conditions**.

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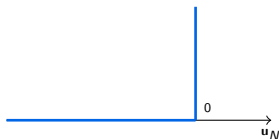
It is given by

$$R_N \in -\frac{\partial \Psi_{\Gamma_c}}{\partial \mathbf{u}_N}$$

that is

$$R_N = \sigma_N \in -\chi u_N - \partial I_{[-\infty, 0]}(u_N)$$

$$\partial I_{[-\infty, 0]}(\mathbf{u}_N) = \begin{cases} 0, & \text{if } \mathbf{u}_N < 0, \\ [0, +\infty), & \text{if } \mathbf{u}_N = 0. \end{cases}$$



## Signorini conditions

$$\sigma_N \in -\chi u_N - \partial I_{[-\infty, 0]}(u_N) \Leftrightarrow u_N \leq 0, \sigma_N + \chi u_N \leq 0, u_N (\sigma_N + \chi u_N) = 0$$

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(classical **Signorini conditions**)

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(classical **Signorini conditions**)

- If the adhesion is **active**  $\chi > 0$

$$\sigma_N \in -\chi u_N - \partial h_{[-\infty, 0]}(u_N)$$

i.e., there is a reaction **counteracting separation**:

$$\sigma_N = -\chi u_N > 0 \text{ if } u_N < 0$$

## The friction effects: the Coulomb law

The **tangential component** of the reaction on  $\Gamma_c$  is given by

$$\mathbf{R}_T \in -\frac{\partial \Phi_{\Gamma_c}}{\partial \dot{\mathbf{u}}_T}$$

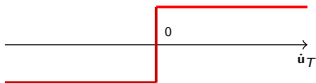
that is

$$\mathbf{R}_T = \sigma_T \in -\chi \mathbf{u}_T - \nu |\sigma_N + \chi u_N| \mathbf{d}(\dot{\mathbf{u}}_T)$$

where

$$\mathbf{d}(\mathbf{v}_T) = \begin{cases} \frac{\mathbf{v}_T}{|\mathbf{v}_T|} & \text{if } \mathbf{v}_T \neq \mathbf{0} \\ \mathbf{z}_T & |\mathbf{z}| \leq 1 \quad \text{if } \mathbf{v}_T = \mathbf{0} \end{cases}$$

$\rightsquigarrow$  if  $v_T$  is scalar, then  $\mathbf{d} = \text{Sign} : \mathbb{R} \rightrightarrows \mathbb{R}$



▶  $\nu$  **friction coefficient**

▶  $\sigma_N + \chi u_N \in -\partial I_{(-\infty, 0]}(u_N)$

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$\sigma_N + \chi u_N \in -\partial l_{(-\infty, 0]}(u_N)$



## The regularized (nonlocal) Coulomb law

The tangential component of the reaction needs to be **regularized**

$$\sigma_T \in -\chi \mathbf{u}_T - \nu |\mathcal{R}(\sigma_N + \chi u_N)| \mathbf{d}(\dot{\mathbf{u}}_T)$$

where



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▶  **$\mathcal{R}$  nonlocal smoothing operator** (physically meaningful)

For friction problems without adhesion, use of  $\mathcal{R}$  first proposed in [Duvaut, '80]

## Nonlocal Coulomb law for unilateral contact

$$\sigma_T \in -\chi \mathbf{u}_T - \nu |\mathcal{R}(\sigma_N + \chi u_N)| \mathbf{d}(\dot{\mathbf{u}}_T)$$

generalizes the **nonlocal** Coulomb law, accounting for adhesion

$$|\sigma_T + \chi \mathbf{u}_T| \leq \nu |\mathcal{R}(\sigma_N + \chi u_N)|,$$

$$|\sigma_T + \chi \mathbf{u}_T| < \nu |\mathcal{R}(\sigma_N + \chi u_N)| \implies \dot{\mathbf{u}}_T = \mathbf{0},$$

$$|\sigma_T + \chi \mathbf{u}_T| = \nu |\mathcal{R}(\sigma_N + \chi u_N)| \implies \exists \lambda \geq 0 : \dot{\mathbf{u}}_T = -\lambda(\sigma_T + \chi \mathbf{u}_T)$$

## The Problem: variational formulation

- Bilinear forms of linear viscoelasticity

$$\begin{cases} a(\mathbf{u}, \mathbf{v}) := \int_{\Omega} a_{ijkl} \varepsilon_{kh}(\mathbf{u}) \varepsilon_{ij}(\mathbf{v}), \\ b(\mathbf{u}, \mathbf{v}) = \int_{\Omega} b_{ijkl} \varepsilon_{kh}(\mathbf{u}) \varepsilon_{ij}(\mathbf{v}) \end{cases}$$

for  $\mathbf{u}, \mathbf{v} \in \mathbf{W} = \{\mathbf{v} \in (H^1(\Omega))^3 : \mathbf{v} = \mathbf{0} \text{ a.e. on } \Gamma_1\}$ .

- **The problem:** Find  $(\mathbf{u}, \chi, \eta)$  such that

$$b(\dot{\mathbf{u}}, \mathbf{v}) + a(\mathbf{u}, \mathbf{v}) + \int_{\Gamma_c} \chi \mathbf{u} \cdot \mathbf{v} + \int_{\Gamma_c} \eta \mathbf{v} \cdot \mathbf{n} + \int_{\Gamma_c} \nu |\mathcal{R}(-\eta)| \mathbf{d}(\dot{\mathbf{u}}_T) \cdot \mathbf{v}_T \ni \langle \mathbf{F}, \mathbf{v} \rangle$$

$\forall \mathbf{v} \in \mathbf{W} \text{ a.e. in } (0, T)$

$$\eta \in \partial I_{(-\infty, 0]}(u_N) \quad \text{on } \Gamma_c \times (0, T)$$

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$$\partial_{\mathbf{n}_s} \chi = 0 \quad \text{on } \partial \Gamma_c \times (0, T) \quad + \text{Cauchy conditions}$$

## Analytical difficulties

$$\begin{aligned}
 & b(\dot{\mathbf{u}}, \mathbf{v}) + a(\mathbf{u}, \mathbf{v}) + \int_{\Gamma_c} \chi \mathbf{u} \mathbf{v} + \int_{\Gamma_c} \eta \mathbf{v} \cdot \mathbf{n} + \\
 & + \int_{\Gamma_c} \nu |\mathcal{R}(-\eta)| \mathbf{d}(\dot{\mathbf{u}}_T) \cdot \mathbf{v}_T \ni \langle \mathbf{F}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{W} \text{ a.e. in } (0, T) \\
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 \end{aligned}$$

↪ **double multivalued constraint** on  $\chi$  and  $\dot{\chi}$

⇒ **doubly nonlinear** character

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 & \partial_{\mathbf{n}_s} \chi = 0 \quad \text{on } \partial \Gamma_c \times (0, T) \quad + \text{Cauchy conditions}
 \end{aligned}$$

↔ **(quadratic) coupling** terms on the **boundary**

⇒ (we need **sufficient regularity** for  $\mathbf{u}$  and  $\dot{\mathbf{u}}$  to control their traces)

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 \end{aligned}$$

↔ **double multivalued constraint** on  $u_N$  and  $\dot{\mathbf{u}}_T$  on the boundary.

⇒ **main difficulty!**

A regularization of the boundary term  $|\mathcal{R}(-\eta)| \mathbf{d}(\dot{\mathbf{u}}_T)$  is **crucial!**

## A global-in-time existence result

$$\begin{aligned}
 & b(\dot{\mathbf{u}}, \mathbf{v}) + a(\mathbf{u}, \mathbf{v}) + \int_{\Gamma_c} \chi \mathbf{u} \mathbf{v} + \int_{\Gamma_c} \eta \mathbf{v} \cdot \mathbf{n} + \\
 & + \int_{\Gamma_c} \nu |\mathcal{R}(-\eta)| |\mathbf{d}(\dot{\mathbf{u}}_T) \cdot \mathbf{v}_T| \ni \langle \mathbf{F}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{W} \text{ a.e. in } (0, T) \\
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 & \partial_{\mathbf{n}_s} \chi = 0 \quad \text{on } \partial \Gamma_c \times (0, T) \quad + \text{Cauchy conditions}
 \end{aligned}$$

There **exists a solution**  $(\mathbf{u}, \chi, \eta)$

$$\mathbf{u} \in H^1(0, T; H^1(\Omega))$$

$$\chi \in W^{1, \infty}(0, T; L^2(\Gamma_c)) \cap H^1(0, T; H^1(\Gamma_c)) \cap L^\infty(0, T; H^2(\Gamma_c))$$

$$\eta \in L^2(0, T; H^{-1/2}(\Gamma_c))$$



## Outline of the proof of existence

- ▶ Moreau-Yosida regularization of non-smooth operators
- ▶ Time discretization scheme (time-incremental minimization)
- ▶ Existence result for the discretized system
- ▶ Uniform estimates
- ▶ Passage to the limit
  - ▶ Identification of nonlinearities

## Outline of the proof of existence

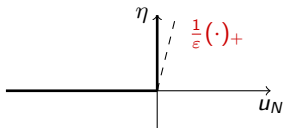
- ▶ **Moreau-Yosida regularization of non-smooth operators**
- ▶ Time discretization scheme (time-incremental minimization)
- ▶ Existence result for the discretized system
- ▶ **Uniform estimates**
- ▶ **Passage to the limit**
  - ▶ **Identification of nonlinearities**

## The approximate problem

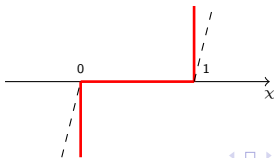
**Approximation:** Moreau-Yosida regularization of the multivalued operators

$$\begin{cases} \partial I_{(-\infty, 0]}(u_N) & \text{replaced by} & (\partial I_{(-\infty, 0]})_{\varepsilon}(u_N) \leftarrow \text{normal compliance} \\ \partial I_{[0, 1]}(\chi) & \text{replaced by} & (\partial I_{[0, 1]})_{\varepsilon}(\chi) \end{cases}$$

- $\eta \in \partial I_{(-\infty, 0]}(u_N) \iff \eta_{\varepsilon} = (\partial I_{(-\infty, 0]})_{\varepsilon}(u_N) = \frac{1}{\varepsilon}(u_N)_{+}$



- $\partial I_{[0, 1]}(\chi) \iff (\partial I_{[0, 1]})_{\varepsilon}(\chi)$



## The approximate problem

$$b(\dot{\mathbf{u}}, \mathbf{v}) + a(\mathbf{u}, \mathbf{v}) + \int_{\Gamma_c} \chi \mathbf{u} \cdot \mathbf{v} + \int_{\Gamma_c} \eta \mathbf{v} \cdot \mathbf{n} + \int_{\Gamma_c} |\mathcal{R}(-\eta)| \mathbf{d}(\dot{\mathbf{u}}_T) \cdot \mathbf{v}_T \ni \langle \mathbf{F}, \mathbf{v} \rangle$$

for all  $\mathbf{v} \in W$  a.e. in  $(0, T)$

$$\eta \in \partial I_{(-\infty, 0]}(u_N) \quad \text{on } \Gamma_c \times (0, T)$$

$$\dot{\chi} - \Delta_s \chi + \partial I_{(-\infty, 0]}(\dot{\chi}) + \partial I_{[0, 1]}(\chi) \ni \omega - \frac{1}{2} |\mathbf{u}|^2 \quad \text{on } \Gamma_c \times (0, T),$$

$$\partial_{n_s} \chi = 0 \quad \text{on } \partial \Gamma_c \times (0, T),$$

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- ▶ Time discretization scheme (time-incremental minimization)
- ▶ Existence result for the discretized system
- ▶ Uniform estimates

## First a priori estimate

- **Energy estimate:**

$$\int_0^t b(\dot{\mathbf{u}}, \dot{\mathbf{u}}) + a(\mathbf{u}, \dot{\mathbf{u}}) + \int_{\Gamma_c} (\chi \mathbf{u} \cdot \dot{\mathbf{u}} + \eta \dot{\mathbf{u}}_N + |\mathcal{R}(-\eta)| \mathbf{d}(\dot{\mathbf{u}}_T) \cdot \dot{\mathbf{u}}_T) \ni \langle \mathbf{F}, \dot{\mathbf{u}} \rangle$$

+

$$\int_0^t \int_{\Gamma_c} \dot{\chi} - \Delta_s \chi + \partial I_{(-\infty, 0]}(\dot{\chi}) + \partial I_{[0, 1]}(\chi) \ni \omega - \frac{1}{2} |\mathbf{u}|^2 \quad \times \quad \dot{\chi}$$

- Some terms cancel out and we get

$$|\mathbf{u}|_{H^1(0, T; W)} \leq C$$

$$|\chi|_{H^1(0, T; L^2(\Gamma_c)) \cap L^\infty(0, T; H^1(\Gamma_c))} \leq C$$

In particular

$$|\mathbf{u}|_{\Gamma_c}|_{H^1(0, T; L^4(\Gamma_c))} \leq C$$

## Second a priori estimate

- Formally

$$\int_0^t \int_{\Gamma_c} \dot{\chi} - \Delta_s \chi + \partial I_{(-\infty, 0]}(\dot{\chi}) + \partial I_{[0, 1]}(\chi) \ni \omega - \frac{1}{2} |\mathbf{u}|^2 \quad \times \quad \partial_t (-\Delta \chi + \partial I_{[0, 1]}(\chi))$$

- Monotonicity** arguments + **integration by parts** in time + **elliptic regularity** ( $\Omega$  suff. smooth) give

$$|\chi|_{H^1(0, T; H^1(\Gamma_c)) \cap L^\infty(0, T; H^2(\Omega))} \leq C$$

$$|\partial I_{[0, 1]}(\chi)|_{L^\infty(0, T; L^2(\Gamma_c))} \leq C$$

& by comparison

$$|\partial I_{(-\infty, 0]}(\dot{\chi})|_{L^\infty(0, T; L^2(\Gamma_c))} \leq C$$

$$|\chi|_{W^{1, \infty}(0, T; L^2(\Gamma_c))} \leq C$$



## Third a priori estimate

- By comparison in the first equation

$$|\partial_t|_{(-\infty,0]}(u_N)\mathbf{n} + |\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T)|_{L^2(0,T;H^{-1/2}(\Gamma_c))} \leq C$$

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$$|\partial l_{(-\infty,0]}(u_N)\mathbf{n} + |\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T)|_{L^2(0,T;H^{-1/2}(\Gamma_c))} \leq C$$

$|\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T)$  &  $\partial l_{(-\infty,0]}(u_N)\mathbf{n}$  are **orthogonal**, hence

$$\begin{cases} |\partial l_{(-\infty,0]}(u_N)\mathbf{n}|_{L^2(0,T;H^{-1/2}(\Gamma_c))} \leq C, \\ ||\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T)|_{L^2(0,T;H^{-1/2}(\Gamma_c))} \leq C \end{cases}$$

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- In addition (from its definition),  
 $|\mathbf{d}(\dot{\mathbf{u}}_T)|_{L^\infty((0,T)\times\Gamma_c)} \leq 1$

## Passage to the limit

- by compactness and monotonicity-semicontinuity arguments
- identification of weak limits for maximal monotone operators
  - ▶ semicontinuity arguments and weak/strong convergence for  $\partial I_{[0,1]}(\chi)$  and  $\partial I_{(-\infty,0]}(\dot{\chi})$
  - ▶ ....
  - ▶ **Main difficulty:** the terms

$$|\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T) \quad \& \quad \eta \in \partial I_{(-\infty,0]}(u_N)$$

simultaneously present in the first equation.

## Identification of the nonlinearities

- ▶ First step: **identification of  $\partial I_{(-\infty, 0]}(u_N)$**   
↪ by semicontinuity, passing to the limit weakly in the first equation
  
- ▶ Second step: **identification of  $|\mathcal{R}(-\eta)|\mathbf{d}(\dot{\mathbf{u}}_T)$**   
↪ by compactifying character of  $\mathcal{R}$ 
  - ▶  $\mathcal{R} : L^2(0, T; H^{-1/2}(\Gamma_c)) \rightarrow L^2(0, T; L^2(\Gamma_c))$
  - ▶ for all  $\eta_\varepsilon, \eta \in L^2(0, T; H^{-1/2}(\Gamma_c))$   
$$\eta_\varepsilon \rightharpoonup \eta \text{ weakly in } L^2(0, T; H^{-1/2}(\Gamma_c))$$
$$\Rightarrow \mathcal{R}(\eta_\varepsilon) \rightarrow \mathcal{R}(\eta) \text{ strongly in } L^2(0, T; L^2(\Gamma_c))$$

## The nonisothermal case

To take into account **thermal effects**:

▶ in the **bulk domain**  $\Omega$ :

▶  $\varepsilon(\mathbf{u})$

▶  $\theta$  (volume absolute temperature)

▶ on the **contact surface**  $\Gamma_C$ :

▶  $\chi$

▶  $\theta_s$  (surface absolute temperature)

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▶  $\chi$

▶  $\theta_s$  (surface absolute temperature)

● **friction coefficient depends on the thermal gap** ( $\theta|_{\Gamma_c} - \theta_s$ )

▶  $\nu \rightsquigarrow \nu(\theta|_{\Gamma_c} - \theta_s)$

▶ **contributions due to friction as source of heat on  $\Gamma_c$**  (*heat generated by friction*).

## The equations for $\theta$ and $\theta_s$

**Entropy balance equations** (rescaled energy balance, under **small perturbation assumption**)

▶ **on the bulk domain:**

$$\left\{ \begin{array}{l} \partial_t s + \operatorname{div} \mathbf{Q} = h \quad \text{in } \Omega \times (0, T), \\ \left\{ \begin{array}{l} \mathbf{Q} \cdot \mathbf{n} = F \quad \text{in } \Gamma_c \times (0, T), \\ \mathbf{Q} \cdot \mathbf{n} = 0 \quad \text{in } \partial\Omega \setminus \Gamma_c \times (0, T), \end{array} \right. \end{array} \right. \quad \left\{ \begin{array}{l} s \text{ volume entropy} \\ \mathbf{Q} \text{ volume entropy flux} \\ F \text{ entropy exchanged through } \Gamma_c \\ h \text{ external source} \end{array} \right.$$

▶ **on the contact surface:**

$$\left\{ \begin{array}{l} \partial_t s_s + \operatorname{div}_s \mathbf{Q}_s = F \quad \text{in } \Gamma_c \times (0, T), \\ \mathbf{Q}_s \cdot \mathbf{n}_s = 0 \quad \text{on } \partial\Gamma_c \times (0, T), \end{array} \right. \quad \left\{ \begin{array}{l} s_s \text{ surface entropy} \\ \mathbf{Q}_s \text{ surface entropy flux} \\ F \text{ entropy exchanged through } \Gamma_c \end{array} \right.$$

♠ **Entropy balance:** see [Bonetti-Colli-Fabrizio-Gilardi '08], also [Bonetti-Colli-Frémond '03, Bonetti-B-Rossi '09.]



Entropy equation for  $\theta$  on the bulk domain

$$\partial_t(\log \theta) - \operatorname{div} \dot{\mathbf{u}} - \Delta \theta = h \quad \text{on } \Omega \times (0, T),$$

$$\partial_n \theta = \begin{cases} 0 & \text{on } \partial\Omega \setminus \Gamma_c \times (0, T), \\ -\chi(\theta - \theta_s) - \nu'(\theta - \theta_s) |\mathcal{R}(-\partial_t]_{-\infty, 0]}(u_N))| |\dot{\mathbf{u}}_T| & \text{on } \Gamma_c \times (0, T), \end{cases}$$

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Entropy equation for  $\theta_s$  on the contact surface

$$\begin{aligned} \partial_t(\log \theta_s) - \lambda'(\chi)\dot{\chi} - \Delta_s \theta_s &= \\ &= \chi(\theta - \theta_s) + \nu'(\theta - \theta_s) |\mathcal{R}(-\partial_{t_{-\infty, 0]}(u_N))| |\dot{\mathbf{u}}_T| \quad \text{in } \Gamma_c \times (0, T) \\ \partial_n \theta_s &= 0 \quad \text{on } \partial\Gamma_c \times (0, T). \end{aligned}$$

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♣ we deduce directly  $\theta, \theta_s > 0$ , crucial for thermodynamical consistency

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- ♣ we deduce directly  $\theta, \theta_s > 0$ , crucial for thermodynamical consistency
- ♠ **singular character of the  $\theta, \theta_s$ -equations** ( $\theta$ -equation is coupled with a third type boundary condition).

## The full system

$$-\operatorname{div}(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\dot{\mathbf{u}}) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T),$$

$$\mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_1 \times (0, T), \quad (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\dot{\mathbf{u}}) + \theta\mathbf{1})\mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_2 \times (0, T),$$

$$(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\dot{\mathbf{u}}) + \theta\mathbf{1})\mathbf{n} + \chi\mathbf{u} + \partial I_{[-\infty, 0]}(u_N)\mathbf{n} + \nu(\theta - \theta_s)|\mathcal{R}(-\partial I_{[-\infty, 0]}(u_N))|\mathbf{d}(\dot{\mathbf{u}}_T) \ni \mathbf{0}$$

$$\dot{\chi} - \Delta_s \chi + \partial I_{[0, 1]}(\chi) \ni \omega - \lambda'(\chi)(\theta_s) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_c \times (0, T),$$

$$\partial_n \chi = 0 \quad \text{on } \partial\Gamma_c \times (0, T)$$

$$\partial_t(\log \theta) - \operatorname{div} \mathbf{u}_t - \Delta \theta = h \quad \text{in } \Omega \times (0, T),$$

$$\partial_n \theta = \begin{cases} 0 & \text{on } \partial\Omega \setminus \Gamma_c \times (0, T), \\ -\chi(\theta - \theta_s) - \nu'(\theta - \theta_s)|\mathcal{R}(-\partial I_{[-\infty, 0]}(u_N))||\dot{\mathbf{u}}_T| & \text{on } \Gamma_c \times (0, T), \end{cases}$$

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$$\partial_n \theta_s = 0 \quad \text{on } \partial\Gamma_c \times (0, T) \quad + \text{Cauchy conditions}$$

$$\begin{aligned}
 & -\operatorname{div}(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\dot{\mathbf{u}}) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\
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 & (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\dot{\mathbf{u}}) + \theta\mathbf{1})\mathbf{n} + \chi\mathbf{u} + \partial_{\mathcal{H}_{-\infty,0]}(u_N)\mathbf{n} + \boxed{\nu(\theta - \theta_s)|\mathcal{R}(-\partial_{\mathcal{H}_{-\infty,0]}(u_N))|\mathbf{d}(\dot{\mathbf{u}}_T)} \ni \mathbf{0}
 \end{aligned}$$

$$\dot{\chi} - \Delta_S \chi + \partial_{\mathcal{H}_{[0,1]}}(\chi) \ni \omega - \lambda'(\chi)(\theta_s) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_c \times (0, T),$$

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$$\partial_t(\log \theta) - \operatorname{div} \mathbf{u}_t - \Delta \theta = h \quad \text{in } \Omega \times (0, T),$$

$$\partial_n \theta = \begin{cases} 0 & \text{on } \partial\Omega \setminus \Gamma_c \times (0, T), \\ -\chi(\theta - \theta_s) - \boxed{\nu'(\theta - \theta_s)|\mathcal{R}(-\partial_{\mathcal{H}_{-\infty,0]}(u_N))||\dot{\mathbf{u}}_T|} & \text{on } \Gamma_c \times (0, T), \end{cases}$$

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♠ **Main difficulty:** **boundary coupling terms** (thermal & frictional effects)

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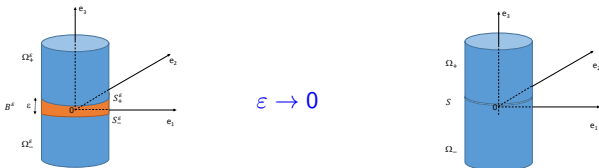
♠ **Main difficulty:** **boundary coupling terms** (thermal & frictional effects)

⇒ we need (...in addition...) **sufficient regularity** on  $\theta$  and  $\dot{\mathbf{u}}$  to control their **traces** ⇨ suitable assumpt. on  $\mathcal{R}$  and  $\nu$  + careful estimates ⇨ **Existence result for the full system**

## An alternative approach: from volume to surface damage

↪ **from volume damage to adhesive contact via dimensional reduction**

↪ to recover the behaviour on **the interface  $S$  as limit of a thin medium** which links the body and the support (or two bodies) and which is ruled by its own evolution law



- ▶ from volume damage to adhesive contact via **asymptotic expansions method** [Bonetti, B., Lebon, Rizzoni '17, Bonetti, B., Lebon '18]
- ▶ from volume damage to delamination/adhesive contact **via variational techniques** [Freddi, Paroni, Roubiřek, Zanini '11, Mielke, Roubiřek, Thomas '12]



# Outlook to the stochastic framework

To take into account

- ▶ unknown distribution of cracks and defects in the material
- ▶ fluctuations/phase changes at the microscopic level



**stochastic models of damage**

## Outlook to the stochastic framework

$$b(\partial_t \mathbf{u}, \mathbf{v}) + a(\mathbf{u}, \mathbf{v}) + \int_{\Gamma_c} \chi \mathbf{u} \cdot \mathbf{v} + \int_{\Gamma_c} \eta \mathbf{v} \cdot \mathbf{n} = \langle \mathbf{F}, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{W} \text{ a.e. in } (0, T)$$
$$\eta \in \partial I_{(-\infty, 0]}(u_N) \quad \text{on } \Gamma_c \times (0, T)$$

$$\partial_t \chi - \Delta_s \chi + \partial I_{[0, 1]}(\chi) \ni \omega - \frac{1}{2} |\mathbf{u}|^2 \quad \text{on } \Gamma_c \times (0, T),$$
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+ *Cauchy conditions*

## Outlook to the stochastic framework

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$$\partial_{\mathbf{n}_s} \chi = 0 \quad \text{on } \partial \Gamma_c \times (0, T)$$

+ *Cauchy conditions*

## A stochastic model of damage [Bauzet, Bonetti, B., Lebon, Vallet, '17]

### Stochastic Allen-Cahn equation with constraint

$$\left\{ \begin{array}{ll} \partial_t \left( \chi - \int_0^t h(\chi) dW \right) - \Delta \chi + \partial I_{[0,1]}(\chi) & \ni w_s(\chi) + f \quad \text{in } \Omega \times D \times (0, T), \\ \partial_n \chi & = 0 \quad \text{in } \Omega \times \partial D \times (0, T), \\ \chi(\omega, x, t = 0) & = \chi_0(x) \quad \omega \in \Omega, x \in D. \end{array} \right.$$

- ▶  $(\Omega, \mathcal{F}, \mathbb{P})$  a probability space,  $D \subset \mathbb{R}^d$ ,  $d \geq 1$
- ▶  $\chi$  the damage parameter,  $0 \leq \chi \leq 1$
- ▶  $w_s : \mathbb{R} \rightarrow [0, +\infty[$  a Lipschitz-continuous function
- ▶  $f : \Omega \times D \times (0, T) \rightarrow \mathbb{R}$  a stochastic process
- ▶  $h : \mathbb{R} \rightarrow \mathbb{R}$  a Lipschitz-continuous function
- ▶  $W = (W_t)_{0 \leq t \leq T}$  a one dimensional Brownian motion defined on  $(\Omega, \mathcal{F}, \mathbb{P})$ .
- ▶  $\chi_0 : D \rightarrow \mathbb{R}$  the initial condition

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- ▶ Moreau-Yosida regularization of  $\partial I_{[0,1]}(\cdot)$
- ▶ Existence and uniqueness for the time discretized system
- ▶ Uniform estimates/passage to the limit procedure

↪ **Existence and uniqueness result**